

# Motif representation using position weight matrix

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# Position weight matrix

- Position weight matrix representation of a motif with width  $w$ :

$$\theta = \begin{bmatrix} \theta_{11} & \theta_{12} & \theta_{13} & \theta_{14} \\ \theta_{21} & \theta_{22} & \theta_{23} & \theta_{24} \\ \dots & & & \\ \theta_{w1} & \theta_{w2} & \theta_{w3} & \theta_{w4} \end{bmatrix} \quad (1)$$

where each row represents one position of the motif, and is normalized:

$$\sum_{j=1}^4 \theta_{ij} = 1 \quad (2)$$

for all  $i = 1, 2, \dots, w$ .

# Likelihood

- Given the position weight matrix  $\theta$ , the probability of generating a sequence  $S = (S_1, S_2, \dots, S_w)$  from  $\theta$  is

$$P(S|\theta) = \prod_{i=1}^w P(S_i|\theta_i) \quad (3)$$

$$= \prod_{i=1}^w \theta_{i,S_i} \quad (4)$$

For convenience, we have converted  $S$  from a string of  $\{A, C, G, T\}$  to a string of  $\{1, 2, 3, 4\}$ .

# Likelihood

- Suppose we observe not just one, but a set of sequences  $S_1, S_2, \dots, S_n$ , each of which contains exactly  $w$  letters. Assume each of them is generated independently from the model  $\theta$ . Then, the likelihood of observing these  $n$  sequences is

$$P(S_1, S_2, \dots, S_n | \theta) = \prod_{k=1}^n P(S_k | \theta) \quad (5)$$

$$= \prod_{k=1}^n \prod_{i=1}^w \theta_{i, S_{ki}} = \prod_{i=1}^w \prod_{j=1}^4 \theta_{ij}^{c_{ij}} \quad (6)$$

where  $c_{ij}$  is the number of letter  $j$  at position  $i$  (Note that  $\sum_{j=1}^4 c_{ij} = n$  for all  $i$ ).

# Parameter estimation

- Now suppose we do not know  $\theta$ . How to estimate it from the observed sequence data  $S_1, S_2, \dots, S_n$ ?
- One solution: calculate the likelihood of observing the provided  $n$  sequences for different values of  $\theta$ ,

$$L(\theta) = P(S_1, S_2, \dots, S_n | \theta) = \prod_{k=1}^n \prod_{i=1}^w \theta_{i, S_{ki}} \quad (7)$$

Pick the one with the largest likelihood, that is, to find  $\theta^*$  that

$$\max_{\theta} P(S_1, S_2, \dots, S_n | \theta) \quad (8)$$

# Maximum likelihood estimation

- Maximum likelihood estimation of  $\theta$  is

$$\hat{\theta}_{ML} = \arg \max_{\theta} \log L(\theta) = \sum_{i=1}^w \sum_{j=1}^4 c_{ij} \log \theta_{ij}$$

$$s.t. \quad \sum_{j=1}^4 \theta_{ij} = 1, \quad \forall i = 1, \dots, w \quad (9)$$

# Optimization with equality constraints

- Construct a Lagrangian function taking the equality constraint into account:

$$g(\theta) = \log L(\theta) + \sum_{i=1}^w \lambda_i \left(1 - \sum_{j=1}^4 \theta_{ij}\right) \quad (10)$$

- Solve the unconstrained optimization problem

$$\hat{\theta} = \arg \max_{\theta} g(\theta) = \sum_{i=1}^w \sum_{j=1}^4 c_{ij} \log \theta_{ij} + \sum_{i=1}^w \lambda_i \left(1 - \sum_{j=1}^4 \theta_{ij}\right) \quad (11)$$

# Optimization with equality constraints

- Take the derivative of  $g(\theta)$  w.r.t.  $\theta_{ij}$  and the Lagrange multiplier  $\lambda_i$  and set them to 0

$$\frac{\partial g(\theta)}{\partial \theta_{ij}} = 0 \quad (12)$$

$$\frac{\partial g(\theta)}{\lambda_i} = 0 \quad (13)$$

which leads to:

$$\hat{\theta}_{ij} = \frac{c_{ij}}{n} \quad (14)$$

which is simply the frequency of different letters at each position. ( $c_{ij}$  is the number of letter  $j$  at position  $i$ ).



# Bayes' Theorem

$$P(\theta|S) = \frac{P(S|\theta)P(\theta)}{P(S)} \quad (15)$$

Each term in Bayes' theorem has a conventional name:

1.  $P(S|\theta)$  – the conditional probability of  $S$  given  $\theta$ , also called the likelihood.
2.  $P(\theta)$  – the prior probability or marginal probability of  $\theta$ .
3.  $P(\theta|S)$  – the conditional probability of  $\theta$  given  $S$ , also called the posterior probability of  $\theta$
4.  $P(S)$  – the marginal probability of  $S$ , and acts as a normalizing constant.

# Maximum a posteriori (MAP) estimation

- MAP (or posterior mode) estimation of  $\theta$  is

$$\hat{\theta}_{\text{MAP}}(S) = \arg \max_{\theta} P(\theta | S_1, S_2, \dots, S_n) \quad (16)$$

$$= \arg \max_{\theta} \log L(\theta) + \log P(\theta) \quad (17)$$

- Assume  $P(\theta) = \prod_{i=1}^w P(\theta_i)$  (independence of  $\theta_i$  at different position  $i$ ).
- Model  $P(\theta_i)$  with a Dirichlet distribution

$$(\theta_{i1}, \theta_{i2}, \theta_{i3}, \theta_{i4}) \sim \text{Dir}(\alpha_1, \alpha_2, \alpha_3, \alpha_4). \quad (18)$$

# Dirichlet Distribution

- Probability density function of Dirichlet distribution  $\text{Dir}(\alpha)$  of order  $K \geq 2$ :

$$p(x_1, \dots, x_K; \alpha_1, \dots, \alpha_K) = \frac{1}{B(\alpha)} \prod_{i=1}^K x_i^{\alpha_i - 1} \quad (19)$$

for all  $x_1, \dots, x_K > 0$  and  $\sum_{i=1}^K x_i = 1$ . The density is zero outside this open  $(K - 1)$ -dimensional simplex.

$\alpha = (\alpha_1, \dots, \alpha_K)$  are parameters with  $\alpha_i > 0$  for all  $i$ .

- $B(\alpha)$ , the normalizing constant, is the multinomial beta function:

$$B(\alpha) = \frac{\prod_{i=1}^K \Gamma(\alpha_i)}{\Gamma(\sum_{i=1}^K \alpha_i)} \quad (20)$$

# Gamma function

- Gamma function for positive real  $z$

$$\Gamma(z) = \int_0^{\infty} t^{z-1} e^{-t} dt \quad (21)$$



$$\Gamma(z + 1) = z\Gamma(z) \quad (22)$$

- If  $n$  is a positive integer, then

$$\Gamma(n + 1) = n! \quad (23)$$

# Properties of Dirichlet distribution

- Dirichlet distribution

$$p(x_1, \dots, x_K; \alpha) = \frac{1}{B(\alpha)} \prod_{i=1}^K x_i^{\alpha_i - 1} \quad (24)$$

- Expectation, define  $\alpha_0 = \sum_{i=1}^K \alpha_i$ ,

$$E[X_i] = \frac{\alpha_i}{\alpha_0} \quad (25)$$

- Variance

$$Var[X_i] = \frac{\alpha_i(\alpha_0 - \alpha_i)}{\alpha_0^2(\alpha_0 + 1)} \quad (26)$$

- Co-variance

$$Cov[X_i X_j] = \frac{-\alpha_i \alpha_j}{\alpha_0^2(\alpha_0 + 1)} \quad (27)$$

# Posterior Distribution

- Conditional probability:

$$P(S_1, S_2, \dots, S_n | \theta) = \prod_{i=1}^w \prod_{j=1}^4 \theta_{ij}^{c_{ij}}$$

- Prior probability:  $p(\theta_{i1}, \dots, \theta_{i4}; \alpha) = \frac{1}{B(\alpha)} \prod_{i=1}^4 \theta_i^{\alpha_i - 1}$

- Posterior probability:

$$P(\theta_i | S_1, \dots, S_n) = \text{Dir}(c_{i1} + \alpha_1, c_{i2} + \alpha_2, c_{i3} + \alpha_3, c_{i4} + \alpha_4)$$

- Maximum a posteriori estimate:

$$\theta_i^{\text{MAP}} = \frac{c_{ij} + \alpha_i - 1}{n + \alpha_0 - 4} \quad (28)$$

where  $\alpha_0 \equiv \sum_i \alpha_i$ .

# Mixture of sequences

- Suppose we have a more difficult situation: Among the set of  $n$  given sequences,  $S_1, S_2, \dots, S_n$ , only a subset of them are generated by a weight matrix model  $\theta$ . How to identify  $\theta$  in this case?
- Let us first define the "*non-motif*" (also called *background*) sequence. Suppose they are generated from a single distribution

$$p^0 = (p_A^0, p_C^0, p_G^0, p_T^0) = (p_1^0, p_2^0, p_3^0, p_4^0) \quad (29)$$

# Likelihood for mixture of sequences

- Now the problem is we do not know which sequence is generated from the motif ( $\theta$ ) and which one is generated from the background model ( $\theta^0$ ).
- Suppose we are provided with such label information:

$$z_i = \begin{cases} 1 & \text{if } S_i \text{ is generated by } \theta \\ 0 & \text{if } S_i \text{ is generated by } \theta^0 \end{cases} \quad (30)$$

for all  $i = 1, 2, \dots, n$ .

- Then, the likelihood of observing the  $n$  sequences

$$P(S_1, S_2, \dots, S_n | z, \theta, \theta^0) = \prod_{i=1}^n [z_i P(S_i | \theta) + (1 - z_i) P(S_i | \theta^0)]$$



# Maximum Likelihood

- Find the joint probability of sequences and the labels

$$\begin{aligned} P(S, z|\theta, \theta^0) &= P(S|z, \theta, \theta^0)P(z) \\ &= \prod_{i=1}^n P(z_i)[z_i P(S_i|\theta) + (1 - z_i)P(S_i|\theta^0)] \end{aligned}$$

where  $z \equiv (z_1, \dots, z_n)$  and  $P(z) = \prod_i P(z_i)$ .

- Marginalize over labels to derive the likelihood

$$L(\theta) = P(S|\theta, \theta^0) = \prod_{i=1}^n [P(z_i = 1)P(S_i|\theta) + P(z_i = 0)P(S_i|\theta^0)]$$

- Maximum likelihood estimate:  $\hat{\theta}_{ML} = \arg \max_{\theta} \log L(\theta)$

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- Marginalize over labels to derive the likelihood

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- Maximum likelihood estimate:  $\hat{\theta}_{ML} = \arg \max_{\theta} \log L(\theta)$

# Lower bound on the $L(\theta)$

- Log likelihood function

$$\log L(\theta) = \sum_{i=1}^n \log [P(z_i = 1)P(S_i|z_i = 1) + P(z_i = 0)P(S_i|z_i = 0)]$$

where  $P(S_i|z_i = 1) = P(S_i|\theta)$  and  $P(S_i|z_i = 0) = P(S_i|\theta_0)$ .

- Jensen's inequality:

$$\log(q_1x + q_2y) \geq q_1 \log(x) + q_2 \log(y)$$

for all  $q_1, q_2 \geq 0$  and  $q_1 + q_2 = 1$ .

# EM-algorithm

- Lower bound on  $\log L(\theta)$ .

$$\log L(\theta) \geq \sum_{i=1}^N \left\{ q_i \log \frac{P(z_i = 1)P(S_i|z_i = 1)}{q_i} + (1 - q_i) \log \frac{P(z_i = 0)P(S_i|z_i = 0)}{1 - q_i} \right\} \equiv \sum_{i=1}^N \phi(q_i, \theta)$$

- Expectation-Maximization: Alternate between two steps:

- E-step

$$\hat{q}_i = \arg \max_{q_i} \phi(q_i, \hat{\theta})$$

- M-step

$$\hat{\theta} = \arg \max_{\theta} \sum_{i=1}^N \phi(\hat{q}_i, \theta)$$

# E-Step

- Auxiliary function

$$\phi(q_i, \theta) = q_i \log \frac{P(z_i = 1)P(S_i|z_i = 1)}{q_i} + (1 - q_i) \log \frac{P(z_i = 0)P(S_i|z_i = 0)}{1 - q_i}$$

- E-step

$$\hat{q}_i = \arg \max_{q_i} \phi(q_i, \hat{\theta})$$

which leads to

$$\hat{q}_i = \frac{P(z_i = 1)P(S_i|z_i = 1)}{P(z_i = 1)P(S_i|z_i = 1) + P(z_i = 0)P(S_i|z_i = 0)} = P(z_i = 1|S_i)$$

# M-Step

- Auxiliary function

$$\phi(q_i, \theta) = q_i \log \frac{P(z_i = 1)P(S_i|z_i = 1)}{q_i} + (1 - q_i) \log \frac{P(z_i = 0)P(S_i|z_i = 0)}{1 - q_i}$$

- M-step

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} \sum_{i=1}^N \phi(\hat{q}_i, \theta) \\ &= \arg \max_{\theta} \sum_{i=1}^N \hat{q}_i [\log P(S_i|\theta) + (1 - \hat{q}_i) \log P(S_i|\theta_0)]\end{aligned}$$

which leads to

$$\hat{\theta}_{ij} = \frac{\sum_{k=1}^N \hat{q}_k I(S_{ki} = j)}{\sum_{k=1}^N \hat{q}_k}$$

where  $I(a)$  is an indicator function:  $I(a) = 1$  if  $a$  is true and 0 *o.w.*

# Summary of EM-algorithm

- Initialize parameters  $\theta$ .
- Repeat until convergence
  - E-step: estimate the expected values of labels, given the current parameter estimate

$$\hat{q}_i = P(z_i | S_i)$$

- M-step: re-estimate the parameters, given the expected estimates of the labels

$$\hat{\theta}_{ij} = \frac{\sum_{k=1}^N \hat{q}_k I(S_{ki} = j)}{\sum_{k=1}^N \hat{q}_k}$$

The procedure is guaranteed to converge to a *local maximum* or *saddle point* solution.

# What about MAP estimate?

Consider a Dirichlet prior distribution on  $\theta_i$ :

$$\theta_i = \text{Dir}(\alpha) \quad \forall i = 1, \dots, w$$

- Initialize parameters  $\theta$ .
- Repeat until convergence
  - E-step: estimate the expected values of labels, given the current parameter estimate

$$\hat{q}_i = P(z_i | S_i)$$

- M-step: re-estimate the parameters, given the expected estimates of the labels

$$\hat{\theta}_{ij} = \frac{\sum_{k=1}^N \hat{q}_k I(S_{ki} = j) + \alpha_j - 1}{\sum_{k=1}^N \hat{q}_k + \alpha_0 - 4}$$



# Different methods for parameter estimation

So far, we have introduced two methods: ML and MAP

- Maximum likelihood (ML)

$$\hat{\theta}_{\text{ML}} = \arg \max_{\theta} P(S|\theta)$$

- Maximum a posterior (MAP)

$$\hat{\theta}_{\text{MAP}} = \arg \max_{\theta} P(\theta|S)$$

- Bayes Estimator

$$\hat{\theta} = \arg \max_{\theta} E \left[ \hat{\theta}(S) - \theta \right]^2$$

that is the one minimizing MSE( mean square error).

$$\hat{\theta} = E[\theta|S] = \int \theta P(\theta|S) d\theta$$

# Joint distribution

- Joint distribution of labels and sequences

$$\begin{aligned} P(S, z|\theta, \theta^0) &= P(S|z, \theta, \theta^0)P(z) \\ &= \prod_{i=1}^n P(z_i)[z_i P(S_i|\theta) + (1 - z_i)P(S_i|\theta^0)] \end{aligned}$$

- Joint distribution of  $S$ ,  $z$ ,  $\theta$  and  $\theta_0$

$$P(S, z, \theta, \theta_0) = \prod_{i=1}^n P(z_i)[z_i P(S_i|\theta) + (1 - z_i)P(S_i|\theta^0)]P(\theta)P(\theta_0)$$

- Find the joint distribution of  $S$  and  $z$

$$P(S, z) = \int_{\theta} \int_{\theta_0} \prod_{i=1}^n P(z_i)[z_i P(S_i|\theta) + (1 - z_i)P(S_i|\theta^0)]P(\theta)P(\theta_0)d\theta_0$$

# Posterior distribution of labels

- Posterior distribution of  $z$ :

$$\begin{aligned}
 P(z|S) &= \int_{\theta} \prod_{i=1}^n P(z_i) [z_i P(S_i|\theta) + (1 - z_i) P(S_i|\theta^0)] P(\theta) d\theta / P(S) \\
 &\sim q^m (1 - q)^{n-m} \prod_{i=1}^w \left[ \int_{\theta_i} \prod_{j=1}^4 \theta_{ij}^{n_{ij}} P(\theta_i) d\theta_i \right] \frac{B(n_0 + \alpha_0)}{B(\alpha_0)} \\
 &\sim q^m (1 - q)^{n-m} \prod_{i=1}^w \left[ \frac{B(n_i + \alpha)}{B(\alpha)} \right] \frac{B(n_0 + \alpha_0)}{B(\alpha_0)}
 \end{aligned}$$

where  $m = \sum_{i=1}^n z_i$ ,  $P(z_i = 1) = q$ ,  $P(\theta_i) = \text{Dir}(\alpha)$ ,  $P(\theta_0) = \text{Dir}(\alpha_0)$  are Dirichlet priors, and

$n_{ij} \equiv \sum_{k=1}^n z_k I(S_{ki} = j)$  is the number of letter  $j$  at position  $i$  among the sequences with label 1.  $n_i \equiv (n_{i1}, \dots, n_{i4})$ .

$n_{0,j} \equiv \sum_{k=1}^n (1 - z_k) \sum_{i=1}^w I(S_{ki} = j)$  and  $n_0 \equiv (n_{0,1}, \dots, n_{0,4})$ .

# Sampling

- Posterior distribution of  $z$ :

$$P(z|S) \sim q^m (1 - q)^{n-m} \prod_{i=1}^w \frac{B(n_i + \alpha)}{B(\alpha)} \frac{B(n_0 + \alpha_0)}{B(\alpha_0)}$$

- Posterior distribution of  $z_k$  conditioned on all other labels

$z_{-k} \equiv \{z_i | i = 1, \dots, n, i \neq k\}$ :

$$P(z_k = 1 | z_{-k}, S) \sim q \prod_{i=1}^w \left[ \frac{B(n_{-k,i} + \Delta(S_{ki}) + \alpha)}{B(n_{-k,i} + \alpha)} \right]$$

where  $n_{-k,ij} \equiv \sum_{l=1, l \neq k}^n z_l I(S_{li} = j)$  is the number of letter  $j$  at position  $i$  among all sequences with label 1 excluding the  $k^{th}$  sequence.  $n_{-k,i} \equiv (n_{-k,i1}, \dots, n_{-k,i4})$ .

$\Delta(l) = (b_1, \dots, b_4)$  with  $b_j = 1$  for  $j = S_{ki}$  and otherwise 0.

# Posterior distribution

- Posterior distribution of  $z_k$  conditioned on  $z_{-k}$ :

$$P(z_k = 1 | z_{-k}, S) \sim q \prod_{i=1}^w \frac{n_{-k, i S_{ki}} + \alpha_{S_{ki}} - 1}{\sum_j [n_{-k, ij} + \alpha_j - 1]} = q \prod_{i=1}^w \theta_{i S_{ki}}$$

Note that  $\theta_{i S_{ki}}$  is same as the MAP estimate of the frequency weight matrix using all sequences with label 1 excluding the  $k^{th}$  sequence.

- Similarly

$$P(z_k = 0 | z_{-k}, S) \sim (1-q) \prod_{i=1}^w \frac{n_{-k, 0 S_{ki}} + \alpha_{0, S_{ki}} - 1}{\sum_j [n_{-k, 0j} + \alpha_{0, j} - 1]} = (1-q) \prod_{i=1}^w \theta_{0, S_{ki}}$$

$\theta_{0, S_{ki}}$  is same as the MAP estimate of the background distribution.

# Gibbs sampling

- Posterior probability

$$P(z_k = 1 | z_{-k}, S) \sim \prod_{i=1}^w \theta_{iS_{ki}}$$

$$P(z_k = 0 | z_{-k}, S) \sim (1 - q) \prod_{i=1}^w \theta_{0,S_{ki}}$$

- Gibbs sampling

$$P(z_k = 1 | z_{-k}, S) = \frac{q \prod_{i=1}^w \theta_{iS_{ki}}}{q \prod_{i=1}^w \theta_{iS_{ki}} + (1 - q) \prod_{i=1}^w \theta_{0,S_{ki}}}$$

# Gibbs sampling

- Initialize labels  $z$ : Assign the value of  $z_i$  randomly according to  $P(z_i = 1) = q$  for all  $i = 1, \dots, n$ .
- Repeat until converge
  - Repeat from  $i = 1$  to  $n$ 
    - Update  $\theta$  matrix using the MAP estimate (excluding  $i^{th}$  sequence)
    - Sample the value of  $z_i$