IMPROVED COMBINATORIAL GROUP TESTING ALGORITHMS FOR REAL-WORLD PROBLEM SIZES*

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Abstract. We study practically efficient methods for performing combinatorial group testing. We present efficient nonadaptive and two-stage combinatorial group testing algorithms, which identify the at most d items out of a given set of n items that are defective, using fewer tests for all practical set sizes. For example, our two-stage algorithm matches the information-theoretic lower bound for the number of tests in a combinatorial group testing regimen.

Key words. combinatorial group testing, Chinese remaindering, Bloom filters

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- 1. Introduction. The problem of combinatorial group testing dates back to World War II, for the problem of determining which in a group of n blood samples contain the syphilis antigen (hence, are contaminated). Formally, in combinatorial group testing, we are given a set of n items, at most d of which are defective (or contaminated), and we are interested in identifying exactly which of the n items are defective. In addition, items can be "sampled" and these samples can be "mixed" together, and so tests for contamination can be applied to arbitrary subsets of these items. The result of a test may be positive, indicating that at least one of the items of that subset is defective, or negative, indicating that all items in that subset are good. Example applications that fit this framework include the following:
 - Screening blood samples for diseases. In this application, items are blood samples and tests are disease detections done on mixtures taken from selected samples.
 - Screening vaccines for contamination. In this case, items are vaccines and tests are cultures done on mixtures of samples taken from selected vaccines.
 - Clone libraries for a DNA sequence. Here, the items are DNA subsequences (called *clones*) and tests are done on pools of clones to determine which clones contain a particular DNA sequence (called a *probe*) [10].
 - Data forensics. In this case, items are documents and the tests are applications of one-way hash functions with known expected values applied to selected collections of documents. The differences from the expected values are then used to identify which, if any, of the documents have been altered.

The primary goal of a testing algorithm is to identify all defective items using as few tests as possible. That is, we wish to minimize the following function:

• t(n,d): the number of tests needed to identify up to d defectives among n items.

This minimization may be subject to possibly additional constraints, as well. For example, we may wish to identify all the defective items in a single (nonadaptive)

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round of testing, we may wish to do this in two (partially-adaptive) rounds, or we may wish to perform the tests sequentially one after the other in a fully adaptive fashion.

In this paper we are interested in efficient solutions to combinatorial group testing problems for realistic problem sizes, which could be applied to solve the motivating examples given above. That is, we wish for solutions that minimize t(n,d) for practical values of n and d as well as asymptotically. Because of the inherent delays that are built into fully adaptive, sequential solutions, we are interested only in solutions that can be completed in one or two rounds. Moreover, we desire solutions that are efficient not only in terms of the total number of tests performed but also for the following measures:

- A(n,t): the analysis time needed to determine which items are defective.
- S(n,d): the sampling rate—the maximum number of tests any item may be included in.

An analysis algorithm is said to be efficient if A(n,t) is O(tn), where n is the number of items and t is the number of tests conducted. It is time-optimal if A(n,t) is O(t). Likewise, we desire efficient sampling rates for our algorithms; that is, we desire that S(n,d) be O(t(n,d)/d). Moreover, we are interested in this paper in solutions that improve previous results, either asymptotically or by constant factors, for realistic problem sizes. We do not define such "realistic" problem sizes formally, but we may wish to consider as unrealistic a problem that is larger than the total memory capacity (in bytes) of all CDs and DVDs in the world ($< 10^{25}$), the number of atomic particles in the earth ($< 10^{50}$), or the number of atomic particles in the universe ($< 10^{80}$).

Viewing testing regimens as matrices. A single round in a combinatorial group testing algorithm consists of a test regimen and an analysis algorithm (which, in a nonadaptive (one-stage) algorithm, must identify all the defectives). The test regimen can be modeled by a $t \times n$ Boolean matrix, M. Each of the n columns of M corresponds to one of the n items. Each of the t rows of M represents a test of items whose corresponding column has a 1-entry in that row. All tests are conducted before the results of any test are made available. The analysis algorithm uses the results of the t tests to determine which of the t items are defective.

As described by Du and Hwang [6, p. 133], the matrix M is d-disjunct if the Boolean sum of any d columns does not contain any other column. In the analysis of a d-disjunct testing algorithm, items included in a test with negative outcome can be identified as pure. Using a d-disjunct matrix enables the conclusion that if there are d or fewer items that cannot be identified as pure in this manner, then all those items must be defective and there are no other defective items. If more than d items remain, then at least d + 1 of them are defective. Thus, using a d-disjunct matrix enables an efficient analysis algorithm, with A(n,t) being O(tn).

M is d-separable (\overline{d} -separable) if the Boolean sums of d (up to d) columns are all distinct. The \overline{d} -separable property implies that each selection of up to d defective items induces a different set of tests with positive outcomes. Thus, it is possible to identify which are the up to d defective items by checking, for each possible selection, whether its induced positive test set is exactly the obtained positive outcomes. However, it might not be possible to detect that there are more than d defective items. This analysis algorithm takes time $\Theta(n^d)$ or requires a large table mapping t-subsets to d-subsets.

Generally, \overline{d} -separable matrices can be constructed with fewer rows than can d-disjunct matrices having the same number of columns. Although the analysis algorithm described above for d-separable matrices is not efficient, some \overline{d} -separable matrices that are not d-disjunct have an efficient analysis algorithm.

Previous related work. Combinatorial group testing is a rich research area with many applications to many other areas, including communications, cryptography, and networking [3]. For an excellent discussion of this topic, the reader is referred to the book by Du and Hwang [6]. For general d, Du and Hwang [6, p. 149] describe a slight modification of the analysis of a construction due to Hwang and Sós [11] that results in a $t \times n$ d-disjunct matrix, with $n \geq (2/3)3^{t/16d^2}$, and so $t \leq 16d^2(1 + \log_3 2 + (\log_3 2) \lg n)$. For two-stage testing, De Bonis, Gasieniec, and Vaccaro [5] provide a scheme that achieves a number of tests within a factor of 7.54(1 + o(1)) of the information-theoretic lower bound of $d \log(n/d)$. For d = 2, Kautz and Singleton [12] construct a 2-disjunct matrix with $t = 3^{q+1}$ and $n = 3^{2^q}$, for any positive integer q. Macula and Reuter [13] describe a $\overline{2}$ -separable matrix and a time-optimal analysis algorithm with $t = (q^2 + 3q)/2$ and $n = 2^q - 1$, for any positive integer q. For d = 3, Du and Hwang [6, p. 159] describe the construction of a $\overline{3}$ -separable matrix (but do not describe the analysis algorithm) with $t = 4\binom{3q}{2} = 18q^2 - 6q$ and $n = 2^q - 1$, for any positive integer q.

Our results. In this paper, we consider problems of identifying defectives using nonadaptive or two-stage protocols with efficient analysis algorithms. We present several such algorithms that require fewer tests than do previous algorithms for practical-sized sets, although we omit the proofs of some supporting lemmas in this paper, due to space constraints. Our general case algorithm, which is based on a method we call the Chinese remainder sieve, improves the construction of Hwang and Sós [11] for all values of d for real-world problem instances as well as for $d \ge n^{1/5}$ and $n \ge e^{10}$. Our two-stage algorithm achieves a bound for t(n,d) that is within a factor of 4(1+o(1)) of the information-theoretic lower bound. This bound improves the bound achieved by De Bonis, Gasieniec, and Vaccaro [5] by almost a factor of 2. Likewise, our algorithm for d=2 improves on the number of tests required for all real-world problem sizes and is time-optimal (that is, with $A(n,t) \in O(t)$). Our algorithm for d=3 is the first known time-optimal testing algorithm for that d-value. Moreover, our algorithms all have efficient sampling rates.

2. The Chinese remainder sieve. In this section, we present a solution to the problem for determining which items are defective when we know that there are at most d < n defectives. Using a simple number-theoretic method, which we call the Chinese remainder sieve method, we describe the construction of a d-disjunct matrix with $t = O(d^2 \log^2 n/(\log d + \log \log n))$. As we will show, our bound is superior to that of the method of Hwang and Sós [11] for all realistic instances of the combinatorial group testing problem.

Suppose we are given n items, numbered $0,1,\ldots,n-1$, such that at most d < n are defective. Let $\{p_1^{e_1},p_2^{e_2},\ldots,p_k^{e_k}\}$ be a sequence of powers of distinct primes, multiplying to at least n^d . That is, $\prod_j p_j^{e_j} \geq n^d$. We construct a $t \times n$ matrix M as the vertical concatenation of k submatrices, M_1,M_2,\ldots,M_k . Each submatrix M_j is a $t_j \times n$ testing matrix, where $t_j = p_j^{e_j}$; hence, $t = \sum_{j=1}^k p_j^{e_j}$. We form each row of M_j by associating it with a nonnegative value x less than $p_j^{e_j}$. Specifically, for each $x, 0 \leq x < p_j^{e_j}$, we form a test in M_j consisting of the item indices (in the range $0,1,\ldots,n-1$) that equal $x \pmod{p_j^{e_j}}$. For example, if x=2 and $p_j^{e_j}=3^2$, then the row for x in M_j has a 1 only in columns 2, 11, 20, and so on.

The following lemma shows that the test matrix M is d-disjunct.

Lemma 1. If there are at most d defective items, and all tests in M are positive for i, then i is defective.

Proof. If all k tests for i (one for each prime power $p_j^{e_j}$) are positive, then there exists at least one defective item. With each positive test that includes i (that is, it has a 1 in column i), let $p_j^{e_j}$ be the modulus used for this test, and associate with j a defective index i_j that was included in that test (choosing i_j arbitrarily in case test j includes multiple defective indices). For any defective index i', let

$$P_{i'} = \prod_{j \text{ s.t. } i_j = i'} p_j^{e_j}.$$

That is, $P_{i'}$ is the product of all the prime powers such that i' caused a positive test that included i for that prime power. Since there are k tests that are positive for i, each $p_j^{e_j}$ appears in exactly one of these products, $P_{i'}$. So $\prod P_{i'} = \prod p_j^{e_j} \geq n^d$. Moreover, there are at most d products, $P_{i'}$. Therefore, $\max_{i'} P_{i'} \geq (n^d)^{1/d} = n$; hence, there exists at least one defective index i' for which $P_{i'} \geq n$. By construction, i' is congruent to the same values to which i is congruent, modulo each of the prime powers in $P_{i'}$. By the Chinese remainder theorem, the solution to these common congruences is unique modulo the least common multiple of these prime powers, which is $P_{i'}$ itself. Therefore, i is equal to i' modulo a number that is at least n, and so i = i'; hence, i is defective. \square

The important role of the Chinese remainder theorem in the proof of the above lemma gives rise to our name for this construction—the Chinese remainder sieve.

Analysis. As mentioned above, the total number of tests, t(n,d), constructed in the Chinese remainder sieve is $\sum_{j=1}^k p_j^{e_j}$, where $\prod p_j^{e_j} \geq n^d$. If we let each $e_j = 1$, we can simplify our analysis to note that $t(n,d) = \sum_{j=1}^k p_j$, where p_j denotes the jth prime number and k is chosen so that $\prod_{j=1}^k p_j \geq n^d$. To produce a closed-form upper bound for t(n,d), we make use of the prime counting function, $\pi(x)$, which is the number of primes less than or equal to x. We also use the well-known Chebyshev function, $\theta(x) = \sum_{j=1}^{\pi(x)} \ln p_j$. In addition, we make use of the following (less well-known) prime summation function, $\sigma(x) = \sum_{j=1}^{\pi(x)} p_j$. Using these functions, we bound the number of tests in the Chinese remainder sieve method as $t(n,d) \leq \sigma(x)$, where x is chosen so that $\theta(x) \geq d \ln n$, since $\lim_{p_j \leq x} p_j = \theta(x)$. For the Chebyshev function, it can be shown [1] that $\theta(x) \geq x/2$ for x > 4 and that $\theta(x) \sim x$ for large x. So if we let $x = \lceil 2d \ln n \rceil$, then $\theta(x) \geq d \ln n$. Thus, we can bound the number of tests in our method as $t(n,d) \leq \sigma(\lceil 2d \ln n \rceil)$. To further bound t(n,d), we use the following lemma, which may be of mild independent interest.

LEMMA 2. For integer $x \geq 2$,

$$\sigma(x) < \frac{x^2}{2\ln x} \left(1 + \frac{1.2762}{\ln x} \right).$$

Proof. Let $n = \pi(x)$. Dusart [7, 8] shows that, for $n \ge 799$,

$$\frac{1}{n}\sum_{j=1}^{n}p_{j}<\frac{1}{2}p_{n};$$

that is, the average of the first n primes is half the value of the nth prime. Thus,

$$\sigma(x) = \sum_{j=1}^{\pi(x)} p_j < \frac{\pi(x)}{2} p_n \le \frac{\pi(x)}{2} x$$

for integer $x \ge 6131$ (the 799th prime). Dusart [7, 8] also shows that

$$\pi(x) < \frac{x}{\ln x} \left(1 + \frac{1.2762}{\ln x} \right)$$

for $x \geq 2$. Therefore, for integer $x \geq 6131$,

$$\sigma(x) < \frac{x^2}{\ln x} \left(1 + \frac{1.2762}{\ln x} \right).$$

In addition, we have verified by an exhaustive computer search that this inequality also holds for all integers $2 \le x < 6131$. This completes the proof.

Thus, we can characterize the Chinese remainder sieve method as follows.

THEOREM 1. Given a set of n items, at most d of which are defective, the Chinese remainder sieve method can identify the defective items using a number of tests

$$t(n,d) < \frac{\lceil 2d \ln n \rceil^2}{2 \ln \lceil 2d \ln n \rceil} \left(1 + \frac{1.2762}{\ln \lceil 2d \ln n \rceil}\right).$$

The sample rate can be bounded by

$$S(n,d) < \frac{\lceil 2d \ln n \rceil}{2 \ln \lceil 2d \ln n \rceil} \left(1 + \frac{1.2762}{\ln \lceil 2d \ln n \rceil} \right),$$

and the analysis time, A(n,t), is O(nt(n,d)).

By calculating the exact numbers of tests required by the Chinese remainder sieve method for particular parameter values and comparing these numbers to the claimed bounds for Hwang and Sós [11], we see that our algorithm is an improvement when

- d = 2 and $n \le 10^{57}$ d = 4 and $n \le 10^{70}$ d = 4 and $n \le 10^{70}$ d = 6 and $n \le 10^{77}$ $d \ge 7$ and $n \le 10^{80}$.

Of course, these are the most likely cases for any expected actual instance of the combinatorial group testing problem. In addition, our analysis shows that our method is superior to the claimed bounds of Hwang and Sós [11] for $d \ge n^{1/5}$ and $n \ge e^{10}$. Less precisely, we can say that t(n,d) is $O(d^2 \log^2 n/(\log d + \log \log n))$, that S(n,d) is $O(d \log n/(\log d + \log \log n))$, and that A(n,t) is O(tn), which is $O(d^2 n \log^2 n/(\log d +$ $\log \log n$).

Heuristic improvements. Although it will not reduce the asymptotic complexity of t, we can reduce the number of tests by starting with a sequence of primes up to some upper bound x and efficiently constructing a set of good prime powers from this sequence. We can allow some powers, e_i , to be zero (meaning that we do not use this prime), while giving others values greater than one. The objective is to choose carefully the values e_j in order to minimize the number of tests while maintaining the property that $\prod p_j^{e_j} \geq n^d$. This typically yields a savings of between five and ten

An example implementation in Python 2.3 is shown in the appendix in Figures A.1 and A.2. This implementation starts with the $e_i = 1$ solution to determine an initial suitable sequence of primes, p_j , to use. It then does a backtracking search to find the optimal set of e_j for these p_j , subject to the constraint that each $p_i^{e_j}$ is not greater than the largest prime in the original solution (with each $e_j = 1$). Since the number of e_j powers is sublogarithmic, and most of them must be 0 or 1, this backtracking search takes time sublinear in n for fixed d.

Table 2.1 Comparing t(n) for d = 5 and d = 10.

(d = 5)	100	10^{4}	10^{6}	10^{8}	10^{10}	10^{20}	10^{30}
Our bktrk	131	378	738	1176	1709	5737	11782
Our genl	160	440	791	1264	1851	6081	12339
HS	2329	4006	5683	7359	9036	17420	25803
(d = 10)	100	10^{4}	10^{6}	108	10^{10}	10^{20}	10^{30}
Our bktrk	378	1176	2350	3896	5737	19681	41020
Our genl	440	1264	2584	4227	6081	20546	42468

Comparison of the number of tests required. Table 2.1 lists the number of tests required by the Hwang-Sós (HS) algorithm, our general algorithm (using the initial set of primes p_j having exponents $e_j = 1$), and our improved backtrack algorithm, for some values of n. As can be seen, for moderate values of n our algorithms require a small fraction of the number of tests required by the HS algorithm. However, asymptotically for fixed d, the HS algorithm requires fewer tests.

3. A two-stage rake-and-winnow protocol. In this section, we present a randomized construction for two-stage group testing. This two-stage method uses a number of tests within a constant factor of the information-theoretic lower bound. It improves previous upper bounds [5] by almost a factor of 2. In addition, it has an efficient sampling rate, with S(n,d) being only $O(\log(n/d))$. All the constant factors "hiding" behind the big-ohs in these bounds are small.

Preliminaries. One of the important tools we use in our analysis is the following lemma for bounding the tail of a certain distribution. It is a form of Chernoff bound [14].

LEMMA 3. Let X be the sum of n independent indicator random variables, such that $X = \sum_{i=1}^{n} X_i$, where each $X_i = 1$ with probability p_i , for i = 1, 2, ..., n. If $E[X] = \sum_{i=1}^{n} p_i \leq \hat{\mu} < 1$, then, for any integer k > 0,

$$\Pr(X \ge k) \le \left(\frac{e\hat{\mu}}{k}\right)^k.$$

Proof. Let $\mu = E[X]$ be the actual expected value of X. Then, by a well-known Chernoff bound [14], for any $\delta > 0$,

$$\Pr[X \ge (1+\delta)\mu] \le \left\lceil \frac{e^{\delta}}{(1+\delta)^{1+\delta}} \right\rceil^{\mu}.$$

(The bound in [14] is for strict inequality, but the same bound holds for nonstrict inequality.) We are interested in the case when $(1+\delta)\mu = k$, that is, when $1+\delta = k/\mu$. Observing that $\delta < 1 + \delta$, we can therefore deduce that

$$\Pr(X \ge k) \le \left\lceil \frac{e^{k/\mu}}{(k/\mu)^{k/\mu}} \right\rceil^{\mu} = \frac{e^k}{(k/\mu)^k} = \left(\frac{e\mu}{k}\right)^k.$$

Finally, noting that $\mu \leq \hat{\mu}$,

$$\Pr(X \ge k) \le \left(\frac{e\hat{\mu}}{k}\right)^k$$
.

In addition to this lemma, we also use the following.

Lemma 4. If d < n, then

$$\binom{n}{d} < \left(\frac{en}{d}\right)^d.$$

Proof.

$$\binom{n}{d} = \frac{n!}{(n-d)! \, d!}$$

$$= \frac{n(n-1)(n-2)\cdots(n-d+1)}{d!}$$

$$< \frac{n^d}{d!}.$$

By Stirling's approximation [4],

$$d! = \sqrt{2\pi n} \left(\frac{d}{e}\right)^d \left(1 + \theta\left(\frac{1}{n}\right)\right).$$

Thus, $d! > (d/e)^d$. Therefore,

$$\frac{n^d}{d!} < \frac{n^d}{(d/e)^d} = \left(\frac{en}{d}\right)^d. \qquad \Box$$

Identifying defective items in two stages. As with our Chinese remainder sieve method, our randomized combinatorial group testing construction is based on the use of a Boolean matrix M where columns correspond to items and rows correspond to tests, so that if M[i,j]=1, then item j is included in test j. Let C denote the set of columns of M. Given a set D of d columns in M, and a specific column $j \in C-D$, we say that j is distinguishable from D if there is a row i of M such that M[i,j]=1 but i contains a 0 in each of the columns in D. Such a property is useful in the context of group testing, for the set D could correspond to the defective items, and if a column j is distinguishable from the set D, then there would be a test in our regimen that would determine that the item corresponding to column j is not defective.

An alternate and equivalent definition [6, p. 165] for a matrix M to be d-disjunct is if, for any d-sized subset D of C, each column in C-D is distinguishable from D. Such a matrix determines a powerful group testing regimen, but, unfortunately, building such a matrix requires M to have $\Omega(d^2 \log n/\log d)$ rows, by a result of Ruszinkó [15] (see also [6, p. 139]). The best known constructions have $\Theta(d^2 \log(n/d))$ rows [6], which is a factor of d greater than information-theoretic lower bound, which is $\Omega(d \log(n/d))$.

Instead of trying to use a matrix M to determine all the defectives immediately, we will settle for a weaker property for M, which nevertheless is still powerful enough to define a good group testing regimen. We say that M is (d,k)-resolvable if, for any d-sized subset D of C, there are fewer than k columns in C-D that are not distinguishable from D. Such a matrix defines a powerful group testing regimen, for defining tests according to the rows of a d-resolvable matrix allows us to restrict the set of defective items to a group D' of smaller than d + k size. Given this set, we can then perform an additional round of individual tests on all the items in D'. This two-stage approach is sometimes called the trivial two-stage algorithm; we refer to this two-stage algorithm as the rake-and-winnow approach.

Thus, a (d, k)-resolvable matrix determines a powerful group testing regimen. Of course, a matrix is d-disjunct iff it is (d, 1)-resolvable. Unfortunately, as mentioned above, constructing a (d, 1)-resolvable matrix requires that the number of rows (which correspond to tests) be significantly greater than the information-theoretical lower bound. Nevertheless, if we are willing to use a (d, k)-resolvable matrix, for a reasonably small value of k, we can come within a constant factor of the information-theoretical lower bound.

Our construction of a (d, k)-resolvable matrix is based on a simple, randomized sample-injection strategy, which itself is based on the approach popularized by the Bloom filter [2]. This novel approach also allows us to provide a strong worst-case bound for the sample rate, S(n,d), of our method. Given a parameter t, which is a multiple of d that will be set in the analysis, we construct a $2t \times n$ matrix M in a columnwise fashion. For each column j of M, we choose t/d rows at random and set the values of these entries to 1. The other entries in column j are set to 0. In other words, we "inject" the sample j into each of the t/d random tests we pick for the corresponding column (since rows of M correspond to tests and the columns correspond to samples). Note, then, that for any set of d defective samples, there are at most t tests that will have positive outcomes and, therefore, at least t tests that will have negative outcomes. The columns that correspond to samples that are distinguishable from the defectives ones can be immediately identified. The remaining issue, then, is to determine the value of t needed so that, for a given value of k, M is a (d, k)-resolvable matrix with high probability.

Let D be a fixed set of d defectives samples. For each (column) item i in C-D, let X_i denote the indicator random variable that is 1 if i is falsely identified as a positive sample by M (that is, i is not included in the set of (negative) items distinguished from those in D), and is 0 otherwise. Observe that the X_i 's are independent, since X_i depends only on whether the choice of rows we picked for column i collide with the at most t rows of M that we picked for the columns corresponding to items in D. Furthermore, this observation implies that any X_i is 1 (a false positive) with probability at most $2^{-t/d}$. Therefore, the expected value of X, E[X], is at most $\hat{\mu} = n/2^{t/d}$. This fact allows us to apply Lemma 3 to bound the probability that M does not satisfy the (d, k)-resolvable property for this particular choice, D, of d defective samples. In particular,

$$\Pr(X \ge k) \le \left(\frac{e\hat{\mu}}{k}\right)^k = \frac{\left(\frac{en}{k}\right)^k}{2^{(t/d)k}}.$$

Note that this bound immediately implies that if k = 1 and $t \ge d(e+1) \log n$, then M will be completely (d, 1)-resolvable with high probability (1 - 1/n) for any particular set of defective items, D.

We are interested, however, in a bound implying that for any subset D of d defectives (of which there are $\binom{n}{d} < (en/d)^d$, by Lemma 4), our matrix M is (d, k)-resolvable with high probability, that is, probability at least 1 - 1/n. That is, we are interested in the value of t such that the above probability bound is $(en/d)^{-d}/n$. From the above probability bound, therefore, we are interested in a value of t such that

$$\frac{2^{(t/d)k}}{\left(\frac{en}{k}\right)^k} \ge \left(\frac{en}{d}\right)^d n.$$

That is, we would like

$$2^{(t/d)k} \ge \left(\frac{en}{d}\right)^d \left(\frac{en}{k}\right)^k n.$$

This bound will hold whenever

$$t \ge (d^2/k)\log(en/d) + d\log(en/k) + (d/k)\log n.$$

Thus, we have the following.

THEOREM 2. If $t \ge (d^2/k) \log(en/d) + d \log(en/k) + (d/k) \log n$, then a $2t \times n$ random matrix M constructed by sample-injection is (d,k)-resolvable with high probability, that is, with probability at least 1 - 1/n.

Taking k = 1, therefore, we have an alternative method for constructing a d-disjunct matrix M with high probability.

COROLLARY 1. If $t \geq d^2 \log(en/d) + d \log en + d \log n$, then a $2t \times n$ random matrix M constructed by sample-injection is d-disjunct with high probability.

That is, we can construct a one-round group test based on sample-injection that uses $O(d^2 \log(n/d))$ tests.

As mentioned above, a productive way of using the sample-injection construction is to build a (d, k)-resolvable matrix M for a reasonably small value of k. We can then use this matrix as the first round in a two-round rake-and-winnow testing strategy, where the second round simply involves our individual testing of the at most d+k samples left as potential positive samples from the first round.

COROLLARY 2. If $t \geq 2d \log(en/d) + \log n$, then the $2t \times n$ random matrix M constructed by sample-injection is (d,d)-resolvable with high probability.

This corollary implies that we can construct a rake-and-winnow algorithm where the first stage involves performing $O(d \log(n/d))$ tests, which is within a (small) constant factor of the information theoretic lower bound, and the second round involves individually testing at most 2d samples.

4. Improved bounds for small d values. In this section, we consider efficient algorithms for the special cases when d=2 and d=3. We present time-optimal algorithms for these cases, that is, with A(n,t) being O(t). Our algorithm for d=3 is the first known such algorithm.

Finding up to two defectives. Consider the problem of determining which items are defective when we know that there are at most two defectives. We describe a $\overline{2}$ -separable matrix and a time-optimal analysis algorithm with $t = (q^2 + 5q)/2$ and $n = 3^q$, for any positive integer q.

Let the number of items be $n = 3^q$, and let the item indices be expressed in radix 3. Index $X = X_{q-1} \cdots X_0$, where each digit $X_p \in \{0, 1, 2\}$.

Hereafter, X ranges over the item index numbers $\{0, \ldots, n-1\}$, p ranges over the radix positions $\{0, \ldots, q-1\}$, and v ranges over the digit values $\{0, 1, 2\}$.

For our construction, matrix M is partitioned into submatrices B and C. Matrix B is the submatrix of M consisting of its first 3q rows. Row $\langle p,v\rangle$ of B is associated with radix position p and value v. $B[\langle p,v\rangle,X]=1$ iff $X_p=v$.

Matrix C is the submatrix of M consisting of its last $\binom{q}{2}$ rows. Row $\langle p, p' \rangle$ of C is associated with distinct radix positions p and p', where p < p'. $C[\langle p, p' \rangle, X] = 1$ iff $X_p = X_{p'}$.

Let $test_B(p, v)$ be the result (1 for positive, 0 for negative) of the test of items having a 1-entry in row $\langle p, v \rangle$ in B. Similarly, let $test_C(p, p')$ be the result of testing row $\langle p, p' \rangle$ in C. Let $test_1(p)$ be the number of different values held by defectives in radix position p. $test_1(p)$ can be computed by $test_B(p, 0) + test_B(p, 1) + test_B(p, 2)$.

The analysis algorithm is shown in the appendix in Figure A.3.

It is easy to determine how many defective items are present. There are no defective items when test1(0) = 0. There is only one defective item when test1(p) = 1

for all p, since if there were two defective items, then there must be at least one position p in which their indices differ and test1(p) would then have value 2. The one defective item has index $D = D_{q-1} \cdots D_0$, where digit D_p is the value v for which $test_B(p, v) = 1$.

Otherwise, there must be two defective items, $D = D_{q-1} \cdots D_0$ and $E = E_{q-1} \cdots E_0$. We iteratively determine the values of the digits of indices D and E.

For radix positions in which defective items exist for only one value of that digit, both D and E must have that value for that digit. For each other radix position, two distinct values for that digit occur in the defective items.

The first radix position in which D and E differ is recorded in the variable p^* and the value of that digit in D (respectively, E) is recorded in v_1^* (respectively, v_2^*).

For any subsequent position p in which D and E differ, the digit values of the defectives in that position are v_a and v_b , which are two distinct values from $\{0, 1, 2\}$, as are v_1^* and v_2^* , and therefore there must be at least one value in common between $\{v_a, v_b\}$ and $\{v_1^*, v_2^*\}$.

Let a common value be v_a and, without loss of generality, let $v_a = v_1^*$.

LEMMA 5. The digit assignment for position p is $D_p = v_a$ and $E_p = v_b$ iff $test_C(p^*, p) = 1$.

Proof. We consider the two possibilities of which defective item has v_a as its digit in position p.

Case 1. $D_p = v_a$.

We see that $D_p = v_a = v_1^*$. Accordingly, a defective (D) would be among the items tested in $test_C(p^*, p)$. Therefore, $test_C(p^*, p) = 1$.

Case 2. $E_p = v_a$.

We see that $D_p \neq v_1^*$, because $D_p \neq E_p = v_a = v_1^*$, and also that $E_p \neq v_2^*$, because $E_p = v_a = v_1^* \neq v_2^*$. Accordingly, neither of the defective items would be among the items tested in $test_C(p^*, p)$. Therefore, $test_C(p^*, p) = 0$.

We have determined the values of defectives D and E for all positions—those where they are the same and those where they differ. For each position, only a constant amount of work is required to determine the assignment of digit values. Therefore, we have proven the following theorem.

THEOREM 3. A $\overline{2}$ -separable matrix that has a time-optimal analysis algorithm can be constructed with $t = (q^2 + 5q)/2$ and $n = 3^q$, for any positive integer q.

Comparison of the number of tests required for the d=2 method. A $\overline{2}$ -separable or a 2-disjunct $t \times n$ matrix enables determination of up to two defective items from among n or fewer items using t tests. An algorithm is more competitive at or just below one of its breakpoints, values of n for which increasing n by one significantly increases t. The Macula–Reuter (MR) algorithm has breakpoints at one under all powers of 2, our (d=2) algorithm at all powers of 3, and the Kautz–Singleton (KS) algorithm at only certain powers of 3. Our general-d algorithms do not have significant breakpoints.

Table 4.1 lists the number of tests required by these algorithms for some small values of n. For all $n \leq 3^{63}$, our d=2 algorithm uses the smallest number of tests. For higher values of $n \leq 3^{130}$, the KS and our d=2 and general (Chinese remainder sieve) algorithms alternate being dominant. The alternations are illustrated in Table 4.2. For all $n \geq 3^{131}$, the HS algorithm uses the fewest tests.

Finding up to three defectives. Consider the problem of determining which items are defective when we know that there are at most three defectives. We describe a $\overline{3}$ -separable matrix and a time-optimal analysis algorithm with $t=2q^2-2q$ and $n=2^q$, for any positive integer q.

Table 4.1 t(n) for small n (d = 2).

(d = 2)	15	100	10^{3}	10^{4}	10^{5}	10^{6}	10^{8}	10^{10}	10^{20}	10^{30}
Our $d=2$	12	25	42	63	88	117	187	273	987	2142
Our bktrk	19	36	60	89	131	168	268	378	1176	2350
Our genl	28	41	77	100	160	197	281	440	1264	2584
MR	14	35	65	119	170	230	405	629	2345	5150
KS	27	81	81	243	243	243	729	729	2187	2187
HS		373	507	641	775	909	1177	1446	2787	4129

Table 4.2 t(n) for large n (d = 2).

(d = 2)	3^{63}	3^{64}	3^{104}	3^{112}	3^{128}	3^{130}	3^{256}
Our $d=2$	2142	2208	5668	6552	8512	8775	33408
Our bktrk	2366	2424	5687	6454	8184	8394	28311
Our genl	2584	2584	6081	6870	8582	8893	29296
KS	2187	2187	6561	6561	6561	19683	19683
HS	4136	4200	6760	7272	8296	8424	16488

Let the number of items be $n=2^q$, and let the item indices be expressed in radix 2. Index $X=X_{q-1}\cdots X_0$, where each digit $X_p\in\{0,1\}$.

Hereafter, X ranges over the item index numbers $\{0, ..., n-1\}$, p ranges over the radix positions $\{0, ..., q-1\}$, and v ranges over the digit values $\{0, 1\}$.

Matrix M has $2q^2 - 2q$ rows. Row $\langle p, p', v, v' \rangle$ of M is associated with distinct radix positions p and p', where p < p', and with values v and v', each of which is in $\{0,1\}$. $M[\langle p, p', v, v' \rangle, X] = 1$ iff $X_p = v$ and $X_{p'} = v'$.

Let $test_M(p, p', v, v')$ be the result (1 for positive, 0 for negative) of testing items having a 1-entry in row $\langle p, p', v, v' \rangle$ in M. For p' > p, define $test_M(p', p, v', v) = test_M(p, p', v, v')$.

The following three functions can be computed in terms of $test_M$.

• $test_B(p, v)$ has value 1 (0) if there are (not) any defectives having value v in radix position p, i.e., $test_B(0, v) = 0$ if $test_M(0, 1, v, 0) + test_M(0, 1, v, 1) = 0$, and 1 otherwise. For p > 0, $test_B(p, v) = 0$ if

$$test_M(p, 0, v, 0) + test_M(p, 0, v, 1) = 0,$$

and 1 otherwise.

- test1(p) is the number of different binary values held by defectives in radix position p. Thus, $test1(p) = test_B(p, 0) + test_B(p, 1)$.
- test2(p, p') is the number of different ordered pairs of binary values held by defectives in the designated ordered pair of radix positions. Therefore,

$$test2(p, p') = test_M(p, p', 0, 0) + test_M(p, p', 0, 1) + test_M(p, p', 1, 0) + test_M(p, p', 1, 1).$$

The analysis algorithm is shown in the appendix in Figure A.4.

We determine the number of defective items and the value of their digits. There are no defective items when test1(0) = 0. Moreover, at each radix position p in which test1(p) = 1, all defective items have the same value of that digit. If all defectives agree on all digit values, then there is only one defective. Otherwise there are at least two defectives, and we need to consider how to assign digit values for only the set of

positions P in which there is at least one defective having each of the two possible binary digit values.

LEMMA 6. There are only two defectives iff, for $p, p' \in P$, test2(p, p') = 2.

Proof. A defective item can contribute at most one new combination of values in positions p, p', and so $test2(p, p') \le the number of defectives. Accordingly, if there are fewer than two defectives, then <math>test2(p, p') < 2$.

If there are exactly two defectives, then $test2(p, p') \le 2$. Since $p \in P$, both binary values appear among defectives, and so $test2(p, p') \ge 2$, and therefore test2(p, p') = 2.

Consider the case in which there are three defectives. In any position p_1 in which both binary values appear at that digit among the set of defectives, one of the defectives (say, D) has one binary value (say, v_1) and the other two defectives (E, F) have the other binary value (\overline{v}_1) . Since E and F are distinct, they must differ in value at some other position p_2 . Therefore, there will be three different ordered pairs of binary values held by defectives in positions p_1 and p_2 , and so $test2(p_1, p_2) = 3$.

Accordingly, if there is no pair of positions for which test2 has value 3, we can conclude that there are only two defectives. Otherwise, there are positions p_1, p_2 for which $test2(p_1, p_2) = 3$, and one of the four combinations of two binary values will not appear. Let that missing combination be v_1, v_2 . Thus, while position p_1 uniquely identifies one defective, say D, as the only defective having value v_1 at that position, position p_2 uniquely identifies one of the other defectives, say E, as having value v_2 .

LEMMA 7. If the position p^* uniquely identifies the defective X to have value v^* , then the value of the defective X at any other position p will be that value v such that $test_M(p^*, p, v^*, v) = 1$.

Proof. If position p^* uniquely identifies defective X as having value v^* , then $X_{p^*} = v^*$ and, for any other defective $Y, Y_{p^*} \neq v^*$.

Let $v = X_p$ for any $p \neq p^*$. Then $test_M(p^*, p, v^*, v) = 1$, since X is a defective that has the required values at the required positions to be included in this test.

Also, $test_M(p^*, p, v^*, \overline{v}) = 0$, because none of the defectives is included in this test. Defective X is not included, because $X_p \neq \overline{v}$. Any other defective, $Y \neq X$, is not included, because $Y_{p^*} \neq v^*$. \square

Since we have positions that uniquely identify D and E, we can determine the values of all their other digits, and the only remaining problem is to determine the values of the digits of defective F.

Since position p_1 uniquely identifies D, we know that $F_{p_1}=\overline{v}_1$. For any other position p, after determining that $E_p=v$, we note that if $test_M(p_1,p,\overline{v}_1,\overline{v})=1$, then there must be at least one defective, X, for which $X_{p_1}=\overline{v}_1$ and $X_p=\overline{v}$. Defective D is ruled out, since $D_{p_1}=v_1$, and defective E is ruled out, since $E_p=v$. Therefore, it must be that $F_p=\overline{v}$. Otherwise, if that $test_M=0$, then $F_p=v$, since $F_p=\overline{v}$ would have caused $test_M=1$.

We have determined the values of defectives D, E, and F for all positions. For each position, only a constant amount of work is required to determine the assignment of digit values. Therefore, we have proven the following theorem.

THEOREM 4. A $\overline{3}$ -separable matrix that has a time-optimal analysis algorithm can be constructed with $t=2q^2-2q$ and $n=2^q$, for any positive integer q.

Comparison of the number of tests required for the d=3 method. The general d algorithm due to Hwang and Sós [11] requires fewer tests than does the Du–Hwang (DH) algorithm for d=3 suggested in [6]. For $n<10^{10}$, our (d=3) algorithm requires even fewer tests and our general (Chinese remainder sieve) algorithm the fewest. However, asymptotically the algorithm of Hwang and Sós uses the fewest

Table 4.3 Comparing t(n) for d = 3.

100	10^{4}	10^{6}	10^{8}	10^{10}	10^{20}	10^{30}
60	168	321	513	738	2350	4777
77	197	381	568	791	2584	5117
84	364	760	1404	2244	8844	19800
838	1442	2046	2649	3253	6271	9289
840	3444	7080	12960	20604	80400	179400
	60 77 84 838	60 168 77 197 84 364 838 1442	60 168 321 77 197 381 84 364 760 838 1442 2046	60 168 321 513 77 197 381 568 84 364 760 1404 838 1442 2046 2649	60 168 321 513 738 77 197 381 568 791 84 364 760 1404 2244 838 1442 2046 2649 3253	60 168 321 513 738 2350 77 197 381 568 791 2584 84 364 760 1404 2244 8844 838 1442 2046 2649 3253 6271

tests. We note that, unlike these other efficient algorithms, our (d = 3) algorithm is time-optimal. Table 4.3 lists the number of tests required by these algorithms for some small values of n.

Appendix A. Pseudocode listings.

```
def eratosthenes():
    """Generate the sequence of prime numbers via the sieve of Eratosthenes."""
   D = \{\} # map composite integers to primes witnessing their compositeness
   q = 2 # first integer to test for primality
   while True:
        if q not in D:
                           # not marked composite, must be prime
           yield q
           D[q*q] = [q]
                          # first multiple of q not already marked
        else:
           for p in D[q]: # move each witness to its next multiple
               D.setdefault(p+q,[]).append(p)
                          # no longer need D[q], free memory
           del D[q]
        q += 1
def search(primes,maxpow,target):
    Backtracking search for exponents of prime powers, each at most maxpow,
    so that the product of the powers is at least target and the sum of the
    nonunit powers is minimized. Returns the pair [sum, list of exponents].
    if target \leq 1:
                           # all unit powers will work?
       return [0,[0]*len(primes)]
    elif not primes or maxpow**len(primes) < target:</pre>
        return None
                           # no primes supplied, no solution exists
                           # list all but the last prime for recursive calls
   primes = list(primes)
   p = primes.pop()
                           \# no solution found yet
   best = None
   i = 0
   while p**i \leq maxpow: # loop through possible exponents of p
        s = search(primes, maxpow, (target + p**i - 1)//p**i)
        if s is not None:
           s[0] += i and p**i
           s [1]. append(i)
           best = min(best,s) or s
        i += 1
   return best
```

Fig. A.1. Subroutines for construction based on prime factorization.

```
\mathbf{def} \ \mathrm{prime\_cgt}(n,d):
      ""Find a CGT for n and d and output a description of it to stdout.""
    # collect primes until their total product is large enough
    primes = []
    product = 1
    for p in eratosthenes():
         primes.append(p)
         product \, *= \, p
         if product > n**d:
              break
     # now find good collection of powers of those primes...
     result = search(primes, primes[-1], n**d)
    powers = result[1]
    \# output results
    print "n =",n,"d =",d,":",
    for i in range(len(primes)):
         if powers[i] == 1:
              print primes[i],
         elif powers[i] > 1:
              print str(primes[i]) + "^" + str(powers[i]),
    \mathbf{print} \ "total \ tests:", \ \mathrm{sum}([\mathrm{primes}[i]**powers[i] \ \mathbf{for} \ i \ \mathbf{in} \ \mathrm{range}(\mathrm{len}(\mathrm{primes}))
                                      if powers[i]])
\mathbf{if} \ \_\mathtt{name}\_== \ "\_\mathit{main}\_":
    for d in range (2,6):
         for x in range (6,16):
              prime\_cgt(1 << x,d)
         print
```

Fig. A.2. Construct tests based on prime factorization.

```
if test1(0) = 0 then return there are no defective items
p^* \leftarrow -1
\mathbf{for}\ p \leftarrow 0\ \mathbf{to}\ q-1\ \mathbf{do}
       if test1(p) = 1 then
              D_p \leftarrow E_p \leftarrow \text{the value } v \text{ such that } test_B(p, v) = 1
                    // test1(p) has value 2
              Let v_1, v_2 be the two values of v such that test_B(p, v) = 1
               if p^* < 0 then
                     v_1^* \leftarrow D_p \leftarrow v_1 
v_2^* \leftarrow E_p \leftarrow v_2
               _{
m else}
                      if test_C(p^*,p)=1 and ( v_1^*=v_1 or v_2^*=v_2 ) then
                             D_p \leftarrow v_1
                             E_p \leftarrow v_2
                             D_p \leftarrow v_2
                             E_p \leftarrow v_1
if p^* < 0 then
       return there is one defective item D
       return there are two defective items D and E
```

Fig. A.3. Analysis algorithm for up to two defectives.

```
if test1(0) = 0 then return there are no defective items
P \leftarrow \emptyset
for p \leftarrow 0 to q - 1 do
       if test1(p) = 1 then
       D_p \leftarrow E_p \leftarrow F_p \leftarrow \text{the value } v \text{ such that } test_B(p,v) = 1 \text{ else } P \leftarrow P \cup \{p\}
if P = \emptyset then return there is one defective item D
if test2(p_1,p_2)=2 for all p_1,p_2\in P then
       for p \in P do
              if p^* < 0 then
                      p^* \leftarrow p
                      v^* \leftarrow D_p \leftarrow 0
               else if test_M(p^*, p, v^*, 0) = 1 then
                            D_p \leftarrow 0
                      else D_p \leftarrow 1
               E_p \leftarrow 1 - D_p
       return there are two defective items D, E
else
       Let p_1, p_2 be positions such that test2(p_1, p_2) = 3
       Let v_1, v_2 be values such that test_M(p_1, p_2, v_1, v_2) = 0
        D_{p_1} \leftarrow v_1
        F_{p_1} \leftarrow E_{p_1} \leftarrow 1 - v_1
       E_{p_2} \leftarrow v_2 
 F_{p_2} \leftarrow D_{p_2} \leftarrow 1 - v_2
       for p \in \hat{P} - \{p_1, p_2\} do
              if test_M(p_1, p, v_1, 0) = 1 then
                     D_p \leftarrow 0
               else D_p \leftarrow 1
               if test_M(p_2, p, v_2, 0) = 1 then
                     E_p \leftarrow 0
               else E_p \leftarrow 1
               v \leftarrow E_p
               if test_M(p_1, p, 1 - v_1, 1 - v) = 1 then
                     F_p \leftarrow 1 - v
               else \vec{F_p} \leftarrow v
return there are three defective items D, E, and F
```

Fig. A.4. Analysis algorithm for up to three defectives.

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