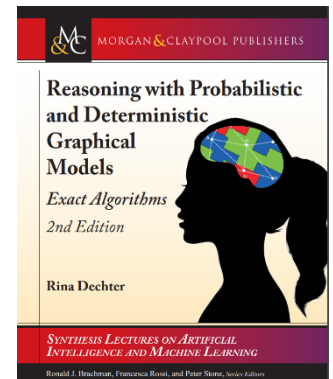


Slides Set 7:
Exact Inference Algorithms
Bucket-elimination

Rina Dechter

(Dechter1 chapter 4, Darwiche chapter 6)





Inference for probabilistic networks

- Bucket elimination
 - Belief-updating, $P(e)$, partition function
 - Marginals, probability of evidence
 - The impact of evidence
 - for MPE (\rightarrow MAP)
 - for MAP (\rightarrow Marginal Map)
 - Mixed networks
- Tree-decomposition schemes
 - Bucket tree elimination
 - Cluster tree elimination

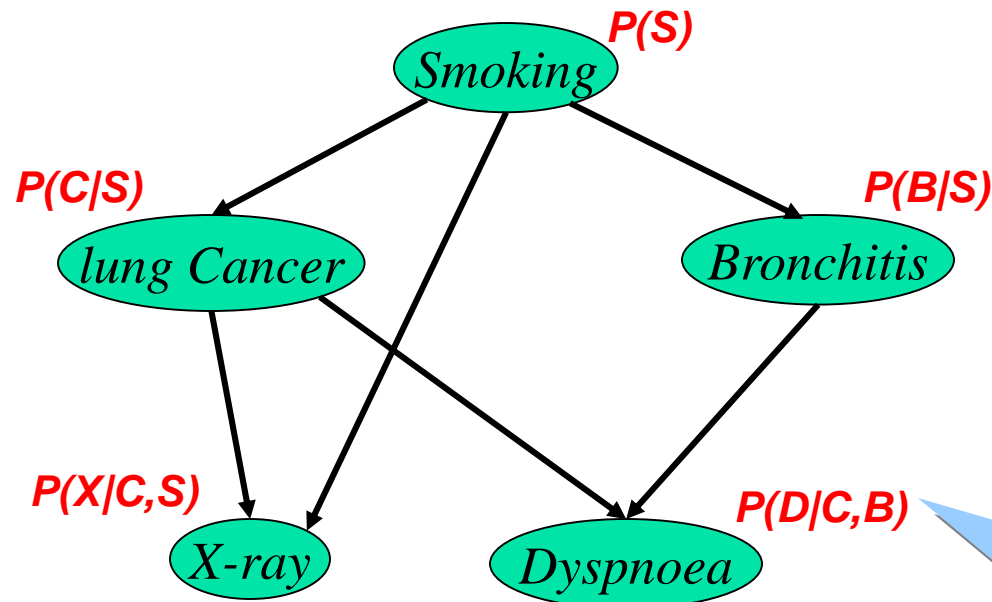


Inference for probabilistic networks

- **Bucket elimination**
 - Belief-updating, $P(e)$, partition function
 - Marginals, probability of evidence
 - The impact of evidence
 - for MPE (\rightarrow MAP)
 - for MAP (\rightarrow Marginal Map)
 - Mixed networks
- Tree-decomposition schemes
 - Bucket tree elimination
 - Cluster tree elimination

Bayesian Networks: Example

(Pearl, 1988)



BN = (G, Θ)

CPD:

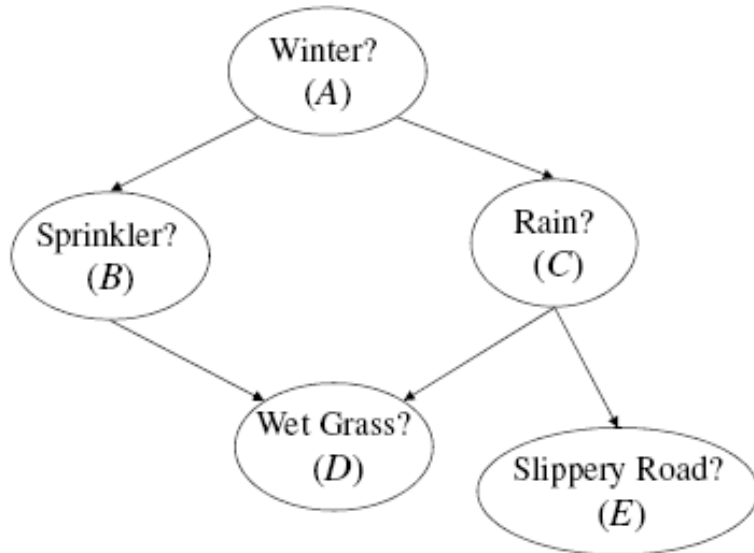
C	B	$P(D C,B)$	
0	0	0.1	0.9
0	1	0.7	0.3
1	0	0.8	0.2
1	1	0.9	0.1

$$P(S, C, B, X, D) = P(S) P(C/S) P(B/S) P(X/C,S) P(D/C,B)$$

Belief Updating:

$P(\text{lung cancer}=\text{yes} \mid \text{smoking}=\text{no}, \text{dyspnoea}=\text{yes}) = ?$

A Bayesian Network



A	Θ_A
true	.6
false	.4

A	B	$\Theta_{B A}$
true	true	.2
true	false	.8
false	true	.75
false	false	.25

A	C	$\Theta_{C A}$
true	true	.8
true	false	.2
false	true	.1
false	false	.9

B	C	D	$\Theta_{D BC}$
true	true	true	.95
true	true	false	.05
true	false	true	.9
true	false	false	.1
false	true	true	.8
false	true	false	.2
false	false	true	0
false	false	false	1

C	E	$\Theta_{E C}$
true	true	.7
true	false	.3
false	true	0
false	false	1

Graphical Models

A **graphical model** consists of:

$X = \{X_1, \dots, X_n\}$ -- variables

$D = \{D_1, \dots, D_n\}$ -- domains

$F = \{f_{\alpha_1}, \dots, f_{\alpha_m}\}$ -- functions or "factors"

Operators:

combination operator
(sum, product, join, ...)

elimination operator
(projection, sum, max, min, ...)

Types of queries:

Marginal: $Z = \sum_{\mathbf{x}} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$

MPE / MAP: $f(\mathbf{x}^*) = \max_{\mathbf{x}} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$

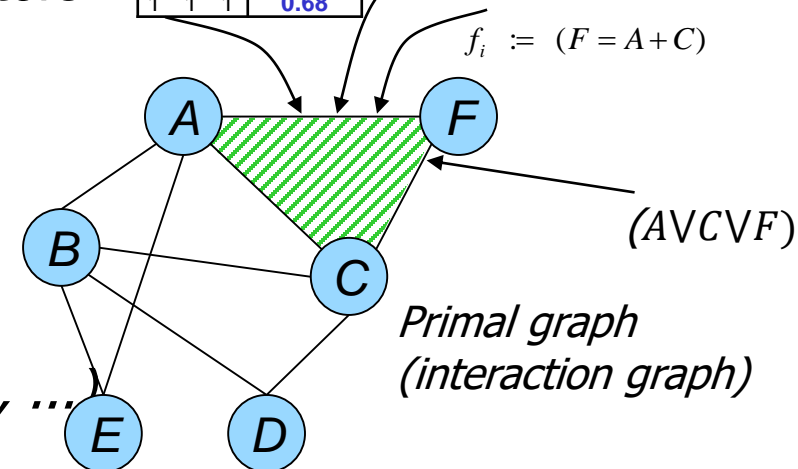
Marginal MAP: $f(\mathbf{x}_M^*) = \max_{\mathbf{x}_M} \sum_{\mathbf{x}_S} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$

Conditional Probability Table (CPT)

A	C	F	P(F A,C)
0	0	0	0.14
0	0	1	0.96
0	1	0	0.40
0	1	1	0.60
1	0	0	0.35
1	0	1	0.65
1	1	0	0.72
1	1	1	0.68

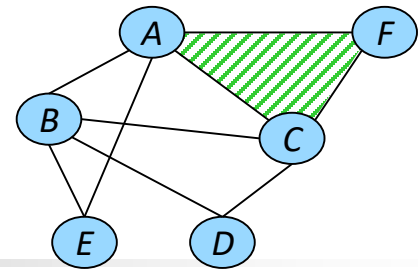
Relation

A	C	F
red	green	blue
blue	red	red
blue	blue	green
green	red	blue

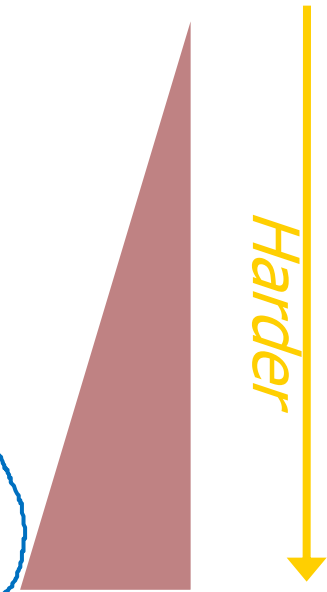


- All these tasks are NP-hard
 - exploit problem structure
 - identify special cases
 - approximate

Types of queries



▶ Max-Inference	$f(\mathbf{x}^*) = \max_{\mathbf{x}} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$
▶ Sum-Inference	$Z = \sum_{\mathbf{x}} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$
▶ Mixed-Inference	$f(\mathbf{x}_M^*) = \max_{\mathbf{x}_M} \sum_{\mathbf{x}_S} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$



- **NP-hard**: exponentially many terms
- We will focus on exact and then on **approximation** algorithms
 - **Anytime**: very fast & very approximate ! Slower & more accurate



Belief Updating is NP-hard

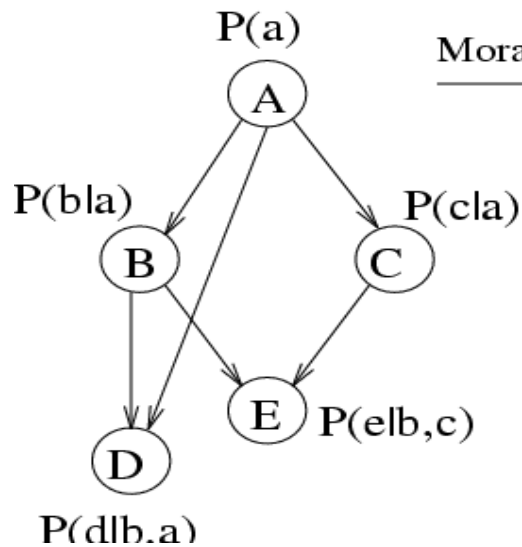
- Each SAT formula can be mapped into a belief updating query in a Bayesian network

- Example

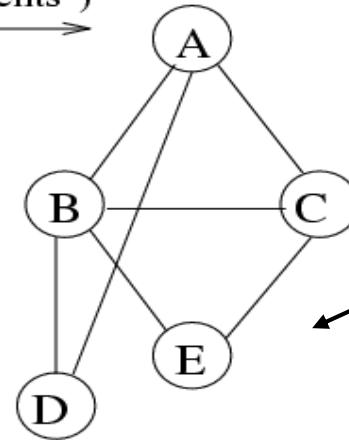
$$(\neg u \vee \neg w \vee y) \wedge (u \vee \neg v \vee w)$$

"Moral" Graph

$$P(X_1, \dots, X_n) = \prod_{i=1}^n \underbrace{P(X_i \mid \text{parents}(X_i))}_{\text{CPT}}$$



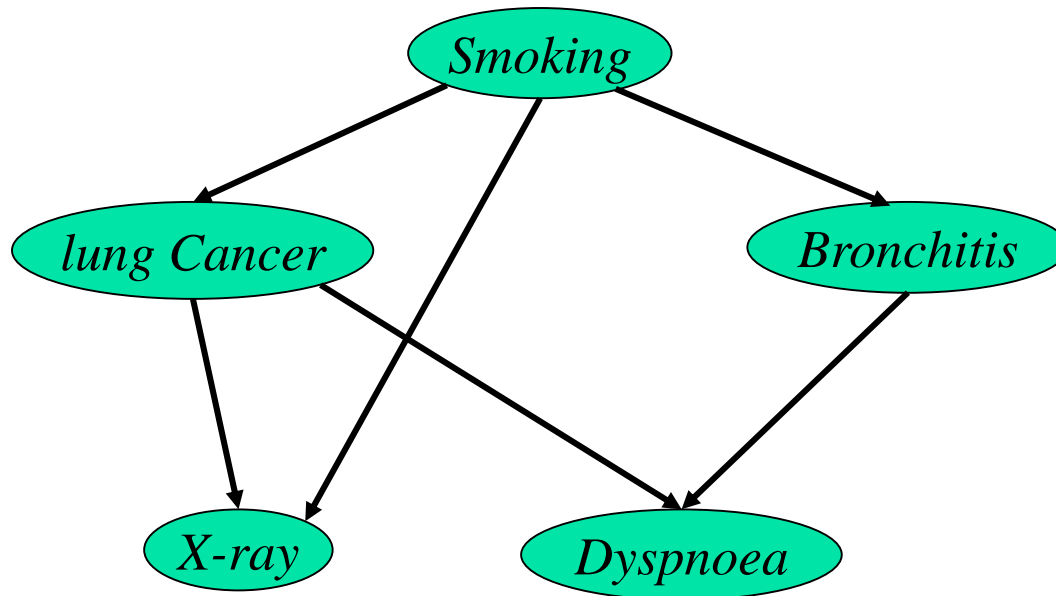
Moralize ("marry parents")



*Conditional
Probability
Distribution
(CPT)*

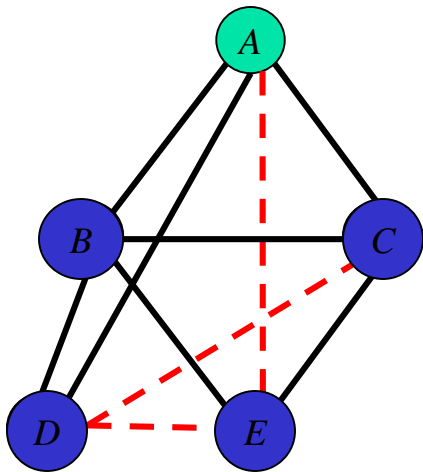
*Clique in
moral graph ("family")*

Belief Updating



$P(\text{lung cancer}=\text{yes} \mid \text{smoking}=\text{no}, \text{dyspnoea}=\text{yes}) = ?$

Belief updating: $P(X|\text{evidence})=?$



"Moral" graph

$$P(a/e=0) \propto P(a, e=0) =$$

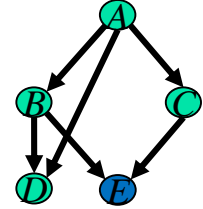
$$\sum_{e=0, d, c, b} P(a) \underbrace{P(b/a)} P(c/a) \underbrace{P(d/b, a) P(e/b, c)} =$$

$$P(a) \sum_{e=0} \sum_d \sum_c P(c/a) \underbrace{\sum_b P(b/a) P(d/b, a) P(e/b, c)}_{h^B(a, d, c, e)}$$

$\swarrow \quad \nwarrow \quad \nearrow \quad \searrow$
 Variable Elimination

Bucket elimination

Algorithm *BE-bel* (Dechter 1996)



$$P(A | E = 0) = \alpha \sum_{E=0, D, C, B} P(A) \cdot P(B | A) \cdot P(C | A) \cdot P(D | A, B) \cdot P(E | B, C)$$

$\sum_b \prod$ ← Elimination operator

bucket B:

$$P(b|a) \quad P(d|b,a) \quad P(e|b,c)$$

bucket C:

$$P(c/a) \quad \lambda^B(\mathbf{a}, \mathbf{d}, \mathbf{c}, \mathbf{e})$$

bucket D:

$$\lambda^C(\mathbf{a}, \mathbf{d}, \mathbf{e})$$

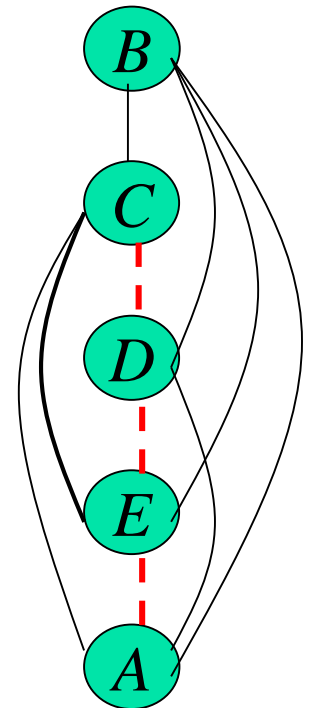
bucket E:

$$e=0 \quad \lambda^D(\mathbf{a}, \mathbf{e})$$

bucket A:

$$P(a) \quad \lambda^E(\mathbf{a})$$

$W^*=4$
"induced width"
(max clique size)



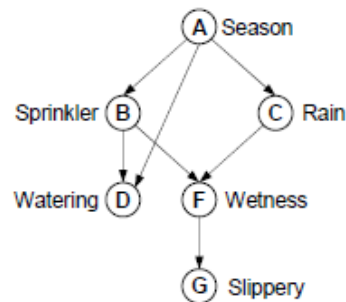
$$P(\mathbf{a}, e=0)$$

$$P(e=0)$$

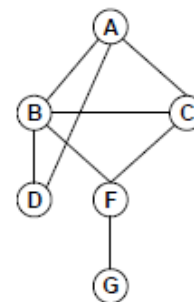
$$P(\mathbf{a} | e=0) = \frac{P(\mathbf{a}, e=0)}{P(e=0)}$$

A Bayesian Network

Ordering: A,C,B,E,D,G



(a) Directed acyclic graph



(b) Moral graph

$$P(a, g = 1) = \sum_{c,b,e,d,g=1} P(a, b, c, d, e, g) = \sum_{c,b,f,d,g=1} P(g|f)P(f|b, c)P(d|a, b)P(c|a)P(b|a)P(a).$$

$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \sum_f P(f|b, c) \sum_d P(d|b, a) \sum_{g=1} P(g|f). \quad (4.1)$$

$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \sum_f P(f|b, c) \lambda_G(f) \sum_d P(d|b, a). \quad (4.2)$$

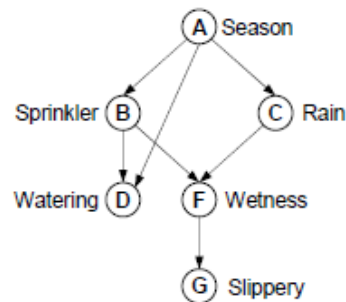
$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \lambda_D(a, b) \sum_f P(f|b, c) \lambda_G(f) \quad (4.3)$$

$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \lambda_D(a, b) \lambda_F(b, c) \quad (4.4)$$

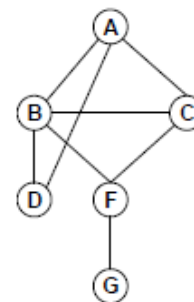
$$P(a, g = 1) = P(a) \sum_c P(c|a) \lambda_B(a, c) \quad (4.5)$$

A Bayesian Network

Ordering: A,C,B,E,D,G



(a) Directed acyclic graph



(b) Moral graph

$$P(a, g = 1) = \sum_{c,b,e,d,g=1} P(a, b, c, d, e, g) = \sum_{c,b,f,d,g=1} P(g|f)P(f|b, c)P(d|a, b)P(c|a)P(b|a)P(a).$$

$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \sum_f P(f|b, c) \sum_d P(d|b, a) \sum_{g=1} P(g|f). \quad (4.1)$$

$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \sum_f P(f|b, c) \lambda_G(f) \sum_d P(d|b, a). \quad (4.2)$$

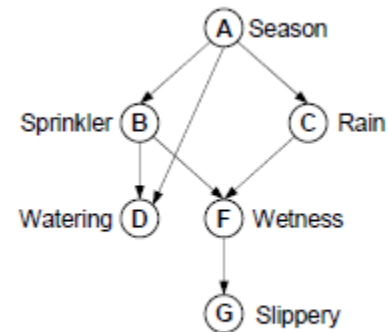
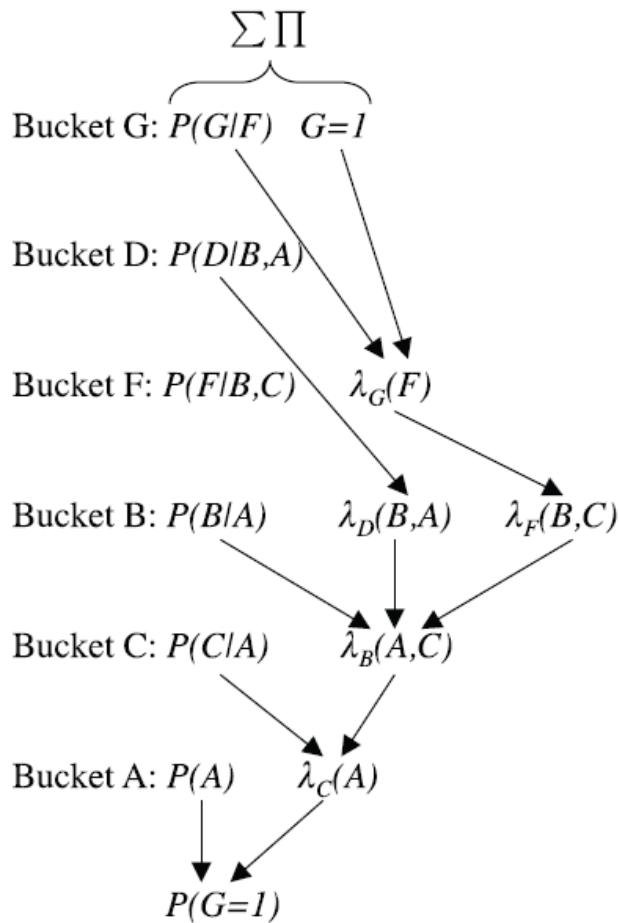
$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \lambda_D(a, b) \sum_f P(f|b, c) \lambda_G(f) \quad (4.3)$$

$$P(a, g = 1) = P(a) \sum_c P(c|a) \sum_b P(b|a) \lambda_D(a, b) \lambda_F(b, c) \quad (4.4)$$

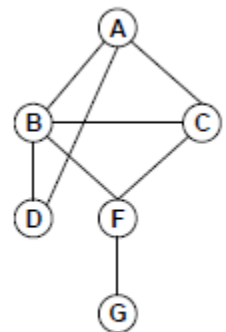
$$P(a, g = 1) = P(a) \sum_c P(c|a) \lambda_B(a, c) \quad (4.5)$$

A Bayesian Network

Ordering: A,C,B,F,D,G

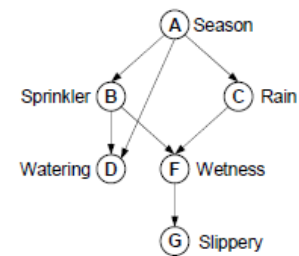


(a) Directed acyclic graph

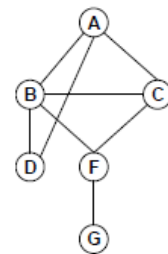


(b) Moral graph

A Different Ordering



(a) Directed acyclic graph



(b) Moral graph

Ordering: A, F, D, C, B, G

$$\begin{aligned}
 P(a, g = 1) &= P(a) \sum_f \sum_d \sum_c P(c|a) \sum_b P(b|a) P(d|a, b) P(f|b, c) \sum_{g=1} P(g|f) \\
 &= P(a) \sum_f \lambda_G(f) \sum_d \sum_c P(c|a) \sum_b P(b|a) P(d|a, b) P(f|b, c) \\
 &= P(a) \sum_f \lambda_G(f) \sum_d \sum_c P(c|a) \lambda_B(a, d, c, f) \\
 &= P(a) \sum_f \lambda_G(f) \sum_d \lambda_C(a, d, f) \\
 &= P(a) \sum_f \lambda_G(f) \lambda_D(a, f) \\
 &= P(a) \lambda_F(a)
 \end{aligned}$$

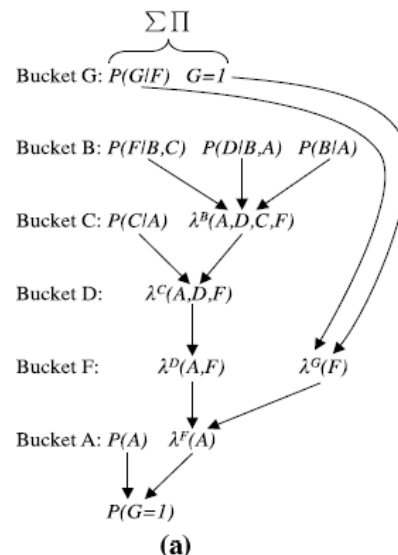
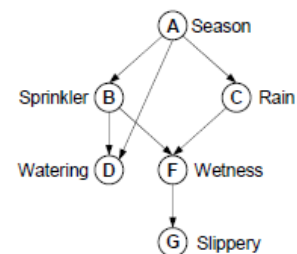
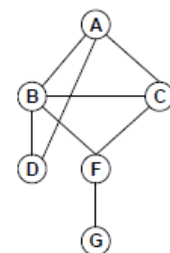


Figure 4.3: The bucket's output when processing along $d_2 = A, F, D, C, B, G$

A Different Ordering



(a) Directed acyclic graph



(b) Moral graph

Ordering: A, F, D, C, B, G

$$\begin{aligned}
 P(a, g = 1) &= P(a) \sum_f \sum_d \sum_c P(c|a) \sum_b P(b|a) P(d|a, b) P(f|b, c) \sum_{g=1} P(g|f) \\
 &= P(a) \sum_f \lambda_G(f) \sum_d \sum_c P(c|a) \sum_b P(b|a) P(d|a, b) P(f|b, c) \\
 &= P(a) \sum_f \lambda_G(f) \sum_d \sum_c P(c|a) \lambda_B(a, d, c, f) \\
 &= P(a) \sum_f \lambda_g(f) \sum_d \lambda_C(a, d, f) \\
 &= P(a) \sum_f \lambda_G(f) \lambda_D(a, f) \\
 &= P(a) \lambda_F(a)
 \end{aligned}$$

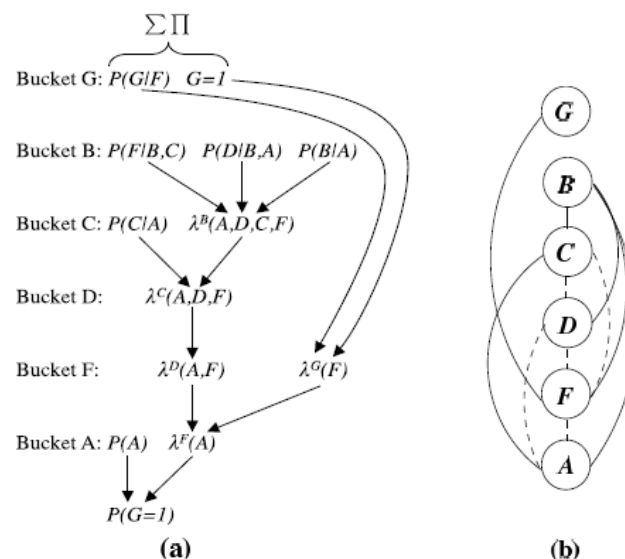
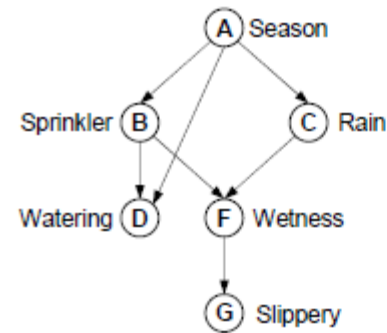
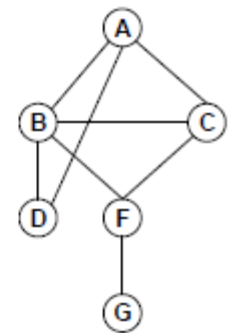


Figure 4.3: The bucket's output when processing along $d_2 = A, F, D, C, B, G$

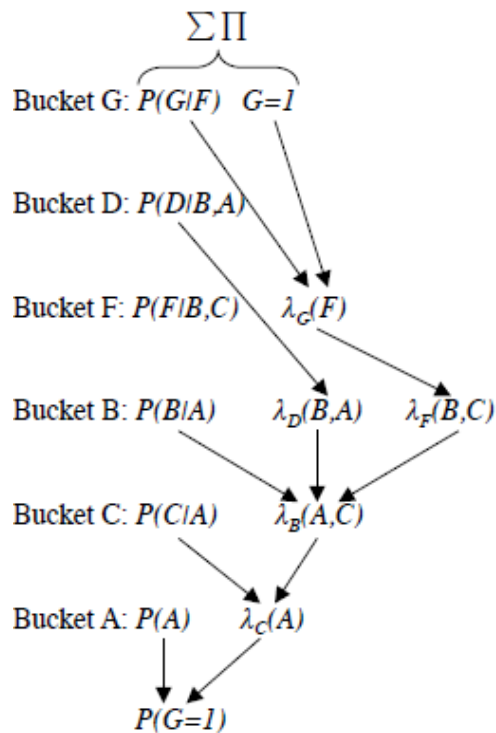
A Bayesian Network Processed Along 2 Orderings



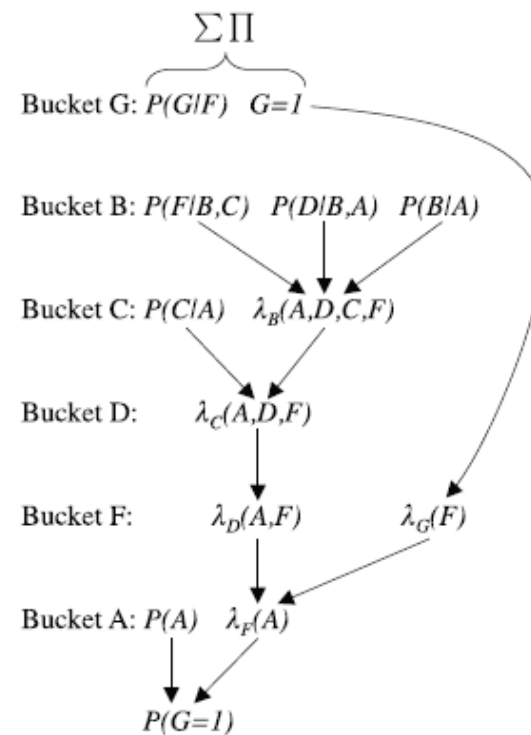
(a) Directed acyclic graph



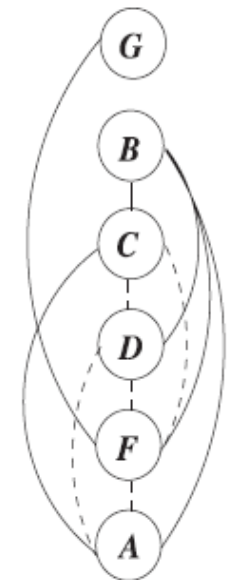
(b) Moral graph



$d_1 = A, C, B, F, D, G$



(a)



(b)

Figure 4.4: The bucket's output when processing along $d_2 = A, F, D, C, B, G$.



The Operation In a Bucket

- Multiplying functions
- Marginalizing (summing-out) functions

Combination of Cost Functions

A	B	f(A,B)
b	b	0.4
b	g	0.1
g	b	0
g	g	0.5

B	C	f(B,C)
b	b	0.2
b	g	0
g	b	0
g	g	0.8

A	B	C	f(A,B,C)
b	b	b	0.1
b	b	g	0
b	g	b	0
b	g	g	0.08
g	b	b	0
g	b	g	0
g	g	b	0
g	g	g	0.4

$= 0.1 \times 0.8$

Factors: Sum-Out Operation

The result of **summing out** variable X from factor $f(\mathbf{X})$

is another factor over variables $\mathbf{Y} = \mathbf{X} \setminus \{X\}$:

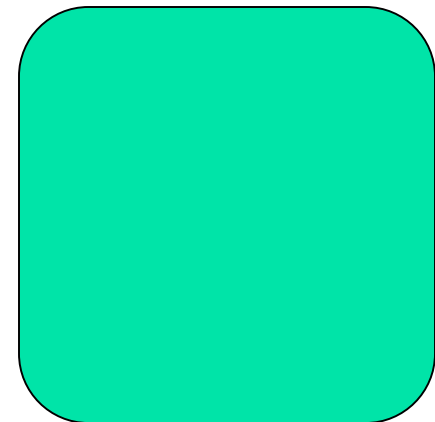
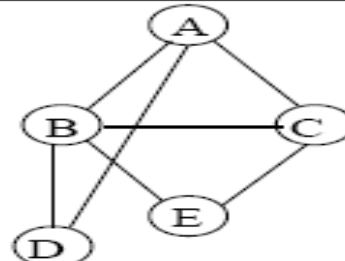
$$\left(\sum_X f \right) (\mathbf{y}) \stackrel{\text{def}}{=} \sum_x f(x, \mathbf{y})$$

B	C	D	f_1
true	true	true	.95
true	true	false	.05
true	false	true	.9
true	false	false	.1
false	true	true	.8
false	true	false	.2
false	false	true	0
false	false	false	1

B	C	$\sum_D f_1$
true	true	1
true	false	1
false	true	1
false	false	1

	$\sum_B \sum_C \sum_D f_1$
T	4

Bucket Elimination and Induced Width



Ordering: a, e, d, c, b

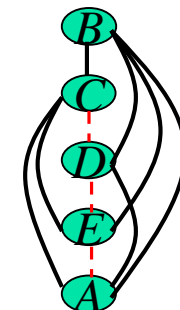
$$\text{bucket}(B) = P(e|b, c), P(d|a, b), P(b|a)$$

$$\text{bucket}(C) = P(c|a) \parallel \lambda_B(a, c, d, e)$$

$$\text{bucket}(D) = \parallel \lambda_C(a, d, e)$$

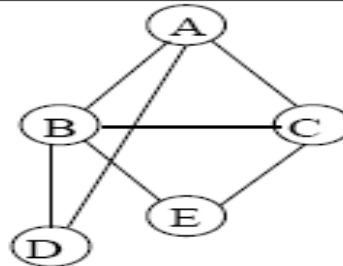
$$\text{bucket}(E) = e = 0 \parallel \lambda_D(a, c)$$

$$\text{bucket}(A) = P(a) \parallel \lambda_E(a)$$



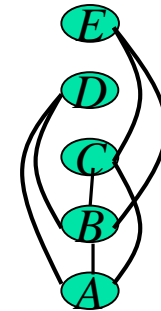
$W^*=4$

Bucket Elimination and Induced Width



Ordering: a, b, c, d, e

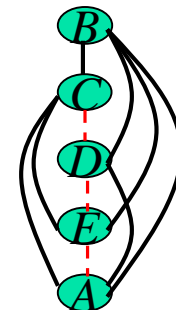
$$\begin{aligned}
 \text{bucket}(E) &= P(e|b, c), \quad e = 0 \\
 \text{bucket}(D) &= P(d|a, b) \\
 \text{bucket}(C) &= P(c|a) \quad || \quad P(e = 0|b, c) \\
 \text{bucket}(B) &= P(b|a) \quad || \quad \lambda_D(a, b), \lambda_C(b, c) \\
 \text{bucket}(A) &= P(a) \quad || \quad \lambda_B(a)
 \end{aligned}$$



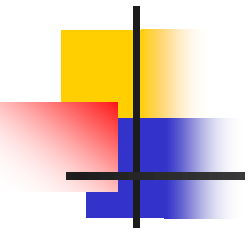
$W^*=2$

Ordering: a, e, d, c, b

$$\begin{aligned}
 \text{bucket}(B) &= P(e|b, c), P(d|a, b), P(b|a) \\
 \text{bucket}(C) &= P(c|a) \quad || \quad \lambda_B(a, c, d, e) \\
 \text{bucket}(D) &= \quad || \quad \lambda_C(a, d, e) \\
 \text{bucket}(E) &= e = 0 \quad || \quad \lambda_D(a, c) \\
 \text{bucket}(A) &= P(a) \quad || \quad \lambda_E(a)
 \end{aligned}$$



$W^*=4$



ALGORITHM BE-BEL

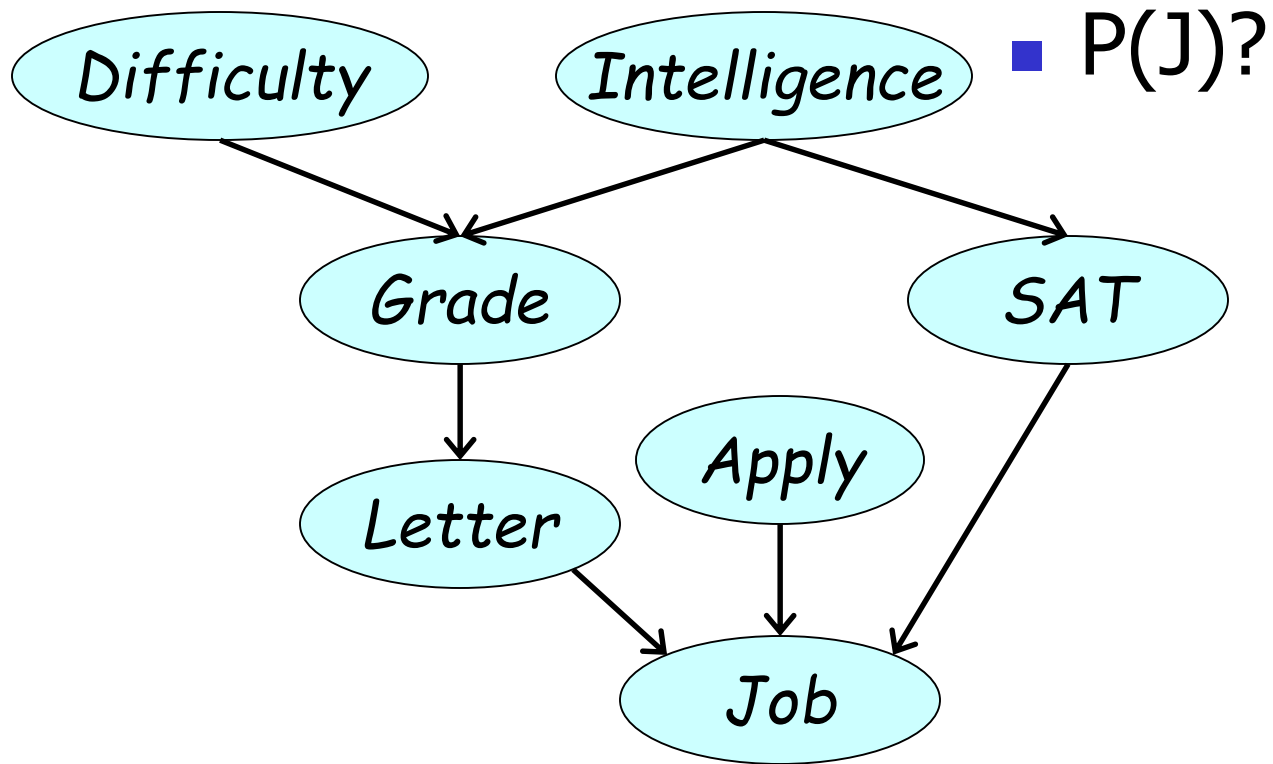
Input: A belief network $\mathcal{B} = \langle X, D, P_G, \Pi \rangle$, an ordering $d = (X_1, \dots, X_n)$; evidence e

output: The belief $P(X_1|e)$ and probability of evidence $P(e)$

1. Partition the input functions (CPTs) into $bucket_1, \dots, bucket_n$ as follows:
for $i \leftarrow n$ **downto** 1, put in $bucket_i$ all unplaced functions mentioning X_i .
Put each observed variable in its bucket. Denote by ψ_i the product of input functions in $bucket_i$.
2. **backward:** for $p \leftarrow n$ **downto** 1 **do**
3. for all the functions $\psi_{S_0}, \lambda_{S_1}, \dots, \lambda_{S_j}$ in $bucket_p$ **do**
If (observed variable) $X_p = x_p$ appears in $bucket_p$,
assign $X_p = x_p$ to each function in $bucket_p$ and then
put each resulting function in the bucket of the *closest* variable in its scope.
else,
4. $\lambda_p \leftarrow \sum_{X_p} \psi_p \cdot \prod_{i=1}^j \lambda_{S_i}$
5. place λ_p in bucket of the latest variable in $scope(\lambda_p)$,
6. **return** (as a result of processing $bucket_1$):
$$P(e) = \alpha = \sum_{X_1} \psi_1 \cdot \prod_{\lambda \in bucket_1} \lambda$$
$$P(X_1|e) = \frac{1}{\alpha} \psi_1 \cdot \prod_{\lambda \in bucket_1} \lambda$$

Figure 4.5: BE-bel: a sum-product bucket-elimination algorithm.

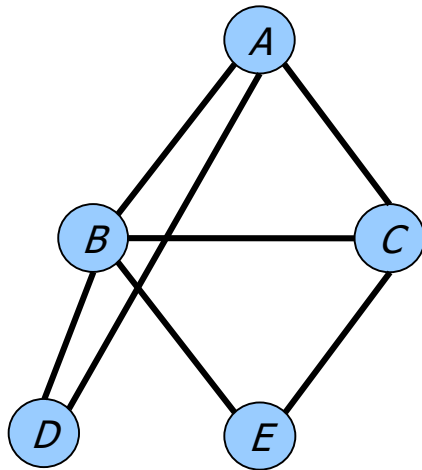
Student Network Example



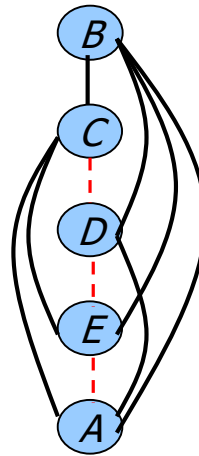
Induced Width (continued)

$w^*(d)$ – the induced width of the primal graph along ordering d

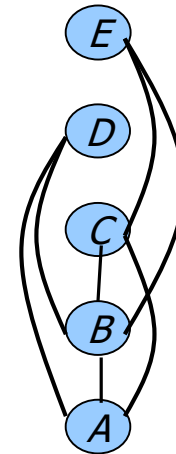
The effect of the ordering:



*Primal (moraal)
graph*



$$w^*(d_1) = 4$$



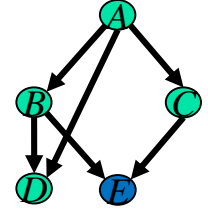
$$w^*(d_2) = 2$$



The impact of evidence

The impact of evidence?

Algorithm *BE-bel*



$$P(A | E = 0) = \alpha \sum_{E=0, D, C, B} P(A) \cdot P(B | A) \cdot P(C | A) \cdot P(D | A, B) \cdot P(E | B, C)$$

$\sum_b \Pi$ ← Elimination operator

bucket B:

$$P(b|a) \quad P(d|b,a) \quad P(e|b,c)$$

$B=1$

bucket C:

$$P(c/a) \quad \lambda^B(a, d, c, e)$$

bucket D:

$$\lambda^C(a, d, e)$$

bucket E:

$$e=0 \quad \lambda^D(a, e)$$

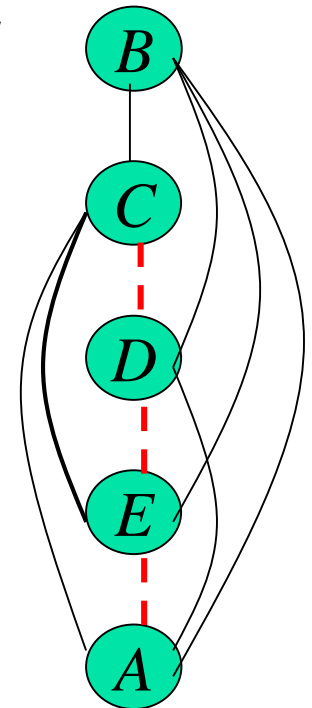
bucket A:

$$P(a) \quad \lambda^E(a)$$

$$P(e=0)$$

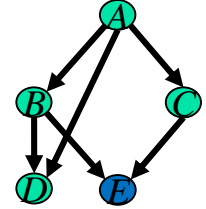
$$P(a|e=0)$$

$W^*=4$
"induced width"
(max clique size)



The impact of evidence?

Algorithm *BE-bel*



$$P(A | E = 0) = \alpha \sum_{E=0, D, C, B} P(A) \cdot P(B | A) \cdot P(C | A) \cdot P(D | A, B) \cdot P(E | B, C)$$

$\sum_b \prod$ ← Elimination operator

bucket B:

$$P(b/a) \quad P(d/b, a) \quad P(e/b, c)$$

$B=1$

bucket C:

$$P(c/a) \quad P(e/b=1, c)$$

bucket D:

$$P(d/b=1, a)$$

bucket E:

$$e=0$$

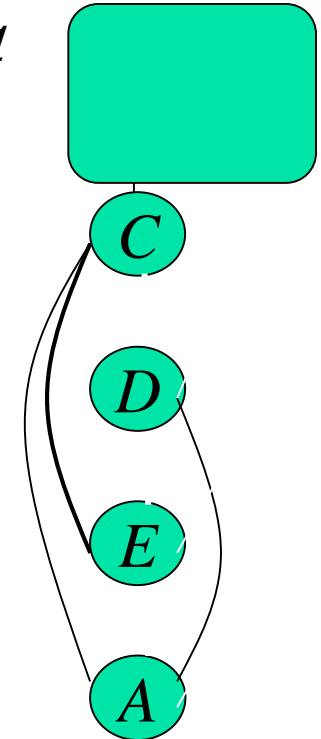
bucket A:

$$P(a) \quad P(b=1/a)$$

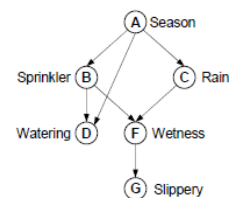
$$P(e=0)$$

$$P(a/e=0)$$

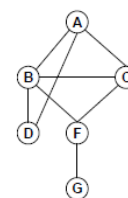
$$P(a|e=0) = \frac{P(a, e=0)}{P(e=0)}$$



The impact of observations



(a) Directed acyclic graph



(b) Moral graph

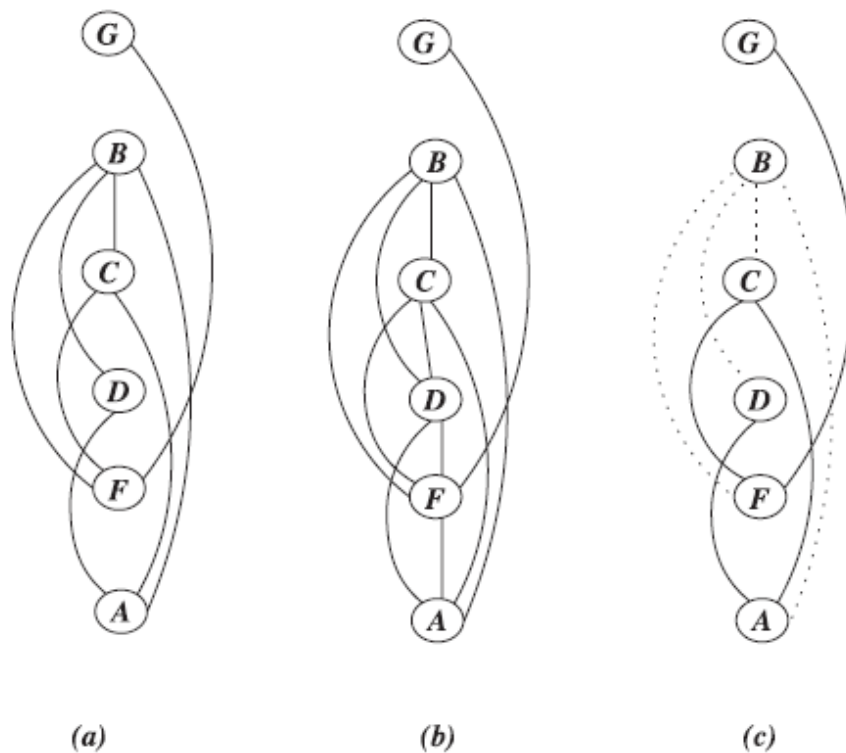


Figure 4.9: Adjusted induced graph relative to observing B .

Ordered graph

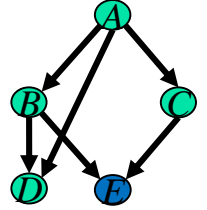
Induced graph

Ordered conditioned graph



Bucket-elimination for MPE (MAP)

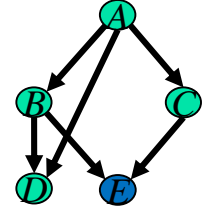
$$MPE = \max_{\bar{x}} P(\bar{x})$$



\sum is replaced by *max* :

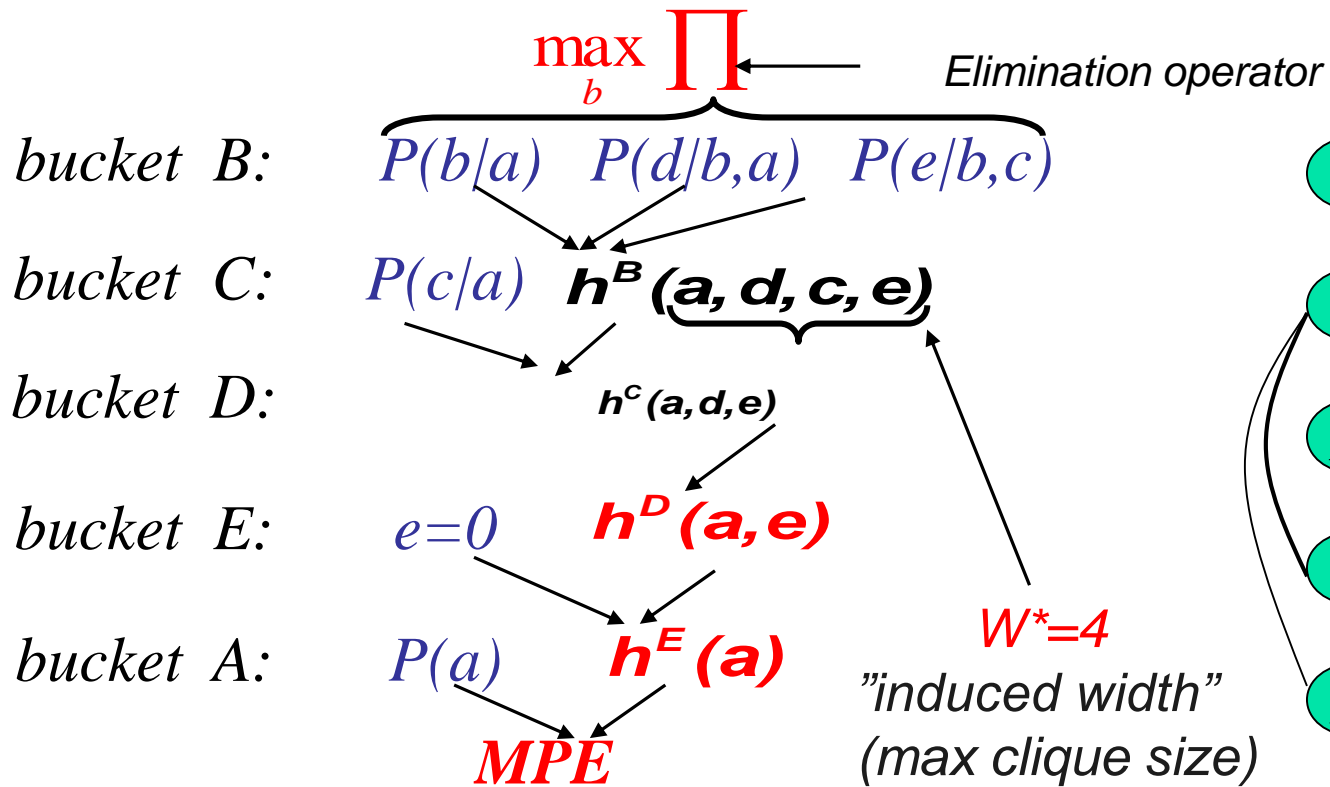
$$MPE = \max_{a,e,d,c,b} P(a)P(c | a)P(b | a)P(d | a,b)P(e | b,c)$$

$$MPE = \max_{\bar{x}} P(\bar{x})$$



\sum is replaced by *max* :

$$MPE = \max_{a,e,d,c,b} P(a)P(c|a)P(b|a)P(d|a,b)P(e|b,c)$$



Generating the MPE-tuple

5. $b' = \arg \max_b P(b | a') \times P(d' | b, a') \times P(e' | b, c')$

4. $c' = \arg \max_c P(c | a') \times h^B(a', d', c, e')$

3. $d' = \arg \max_d h^C(a', d, e')$

2. $e' = 0$

1. $a' = \arg \max_a P(a) \cdot h^E(a)$

B: $P(b/a) \quad P(d/b,a) \quad P(e/b,c)$

C: $P(c/a) \quad h^B(a, d, c, e)$

D: $h^C(a, d, e)$

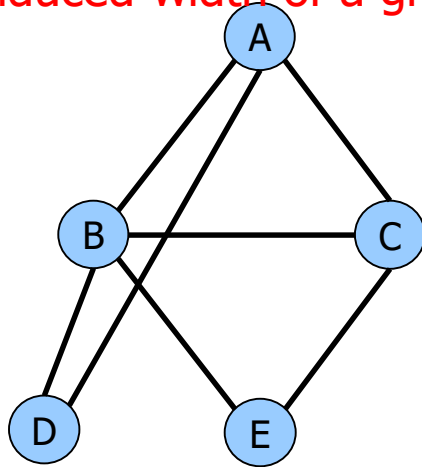
E: $e=0 \quad h^D(a, e)$

A: $P(a) \quad h^E(a)$

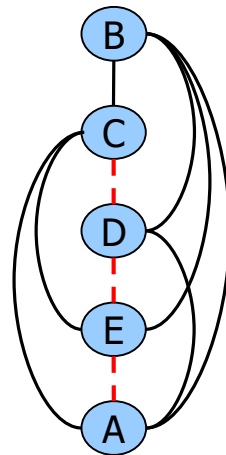
Return (a', b', c', d', e')

Induced Width

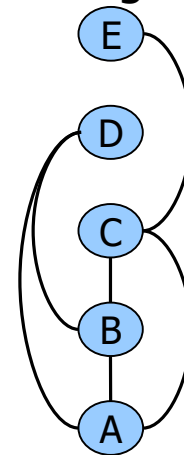
- **Width** is the max number of parents in the ordered graph
- **Induced-width** is the width of the induced ordered graph: recursively connecting parents going from last node to first.
- **Induced-width $w^*(d)$** is the max induced-width over all nodes in ordering d
- **Induced-width of a graph, w^*** is the min $w^*(d)$ over all orderings d



primal
graph



$$w^*(d_1) = 4$$



$$w^*(d_2) = 2$$

Complexity of Bucket Elimination

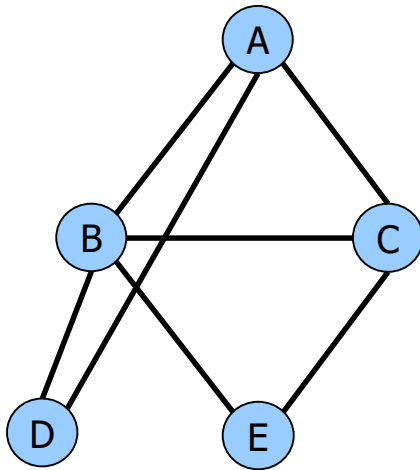
*Bucket-Elimination is **time and space***

$$O(r \exp(w_d^*))$$

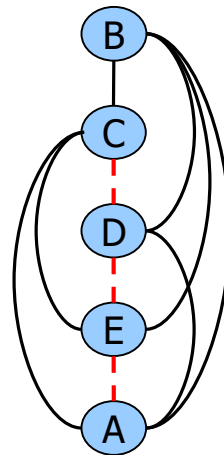
w_d^* : the induced width of the primal graph along ordering d

r = number of functions

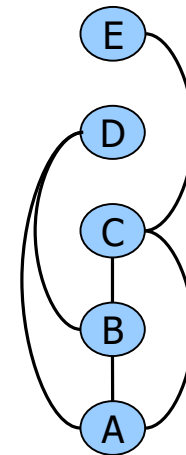
The effect of the ordering:



primal
graph



$$w^*(d_1) = 4$$

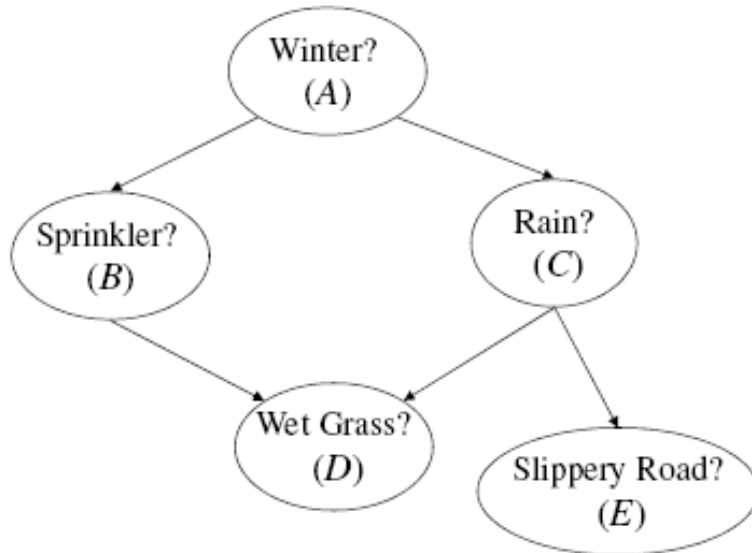


$$w^*(d_2) = 2$$

Finding smallest induced-width is hard!

A Bayesian Network

Example with mpe?



A	Θ_A
true	.6
false	.4

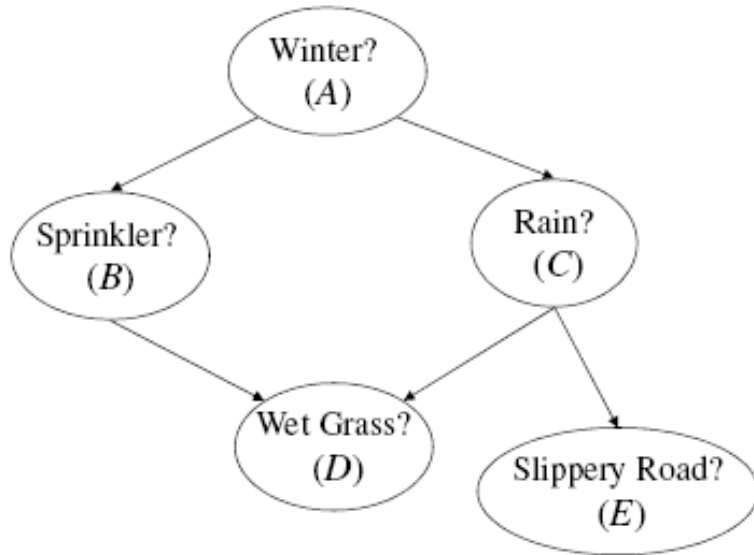
A	B	$\Theta_{B A}$
true	true	.2
true	false	.8
false	true	.75
false	false	.25

A	C	$\Theta_{C A}$
true	true	.8
true	false	.2
false	true	.1
false	false	.9

B	C	D	$\Theta_{D BC}$
true	true	true	.95
true	true	false	.05
true	false	true	.9
true	false	false	.1
false	true	true	.8
false	true	false	.2
false	false	true	0
false	false	false	1

C	E	$\Theta_{E C}$
true	true	.7
true	false	.3
false	true	0
false	false	1

Try to compute MPE when $E=0$



A	Θ_A
true	.6
false	.4

A	B	$\Theta_{B A}$
true	true	.2
true	false	.8
false	true	.75
false	false	.25

A	C	$\Theta_{C A}$
true	true	.8
true	false	.2
false	true	.1
false	false	.9

B	C	D	$\Theta_{D BC}$
true	true	true	.95
true	true	false	.05
true	false	true	.9
true	false	false	.1
false	true	true	.8
false	true	false	.2
false	false	true	0
false	false	false	1

C	E	$\Theta_{E C}$
true	true	.7
true	false	.3
false	true	0
false	false	1

Cost Networks

$$P(a, b, c, d, f, g) = P(a)P(b|a)P(c|a)P(f|b, c)P(d|a, b)P(g|f)$$

becomes

$$C(a, b, c, d, e) = -\log P = C(a) + C(b, a) + C(c, a) + C(f, b, c) + C(d, a, b) + C(g, f)$$

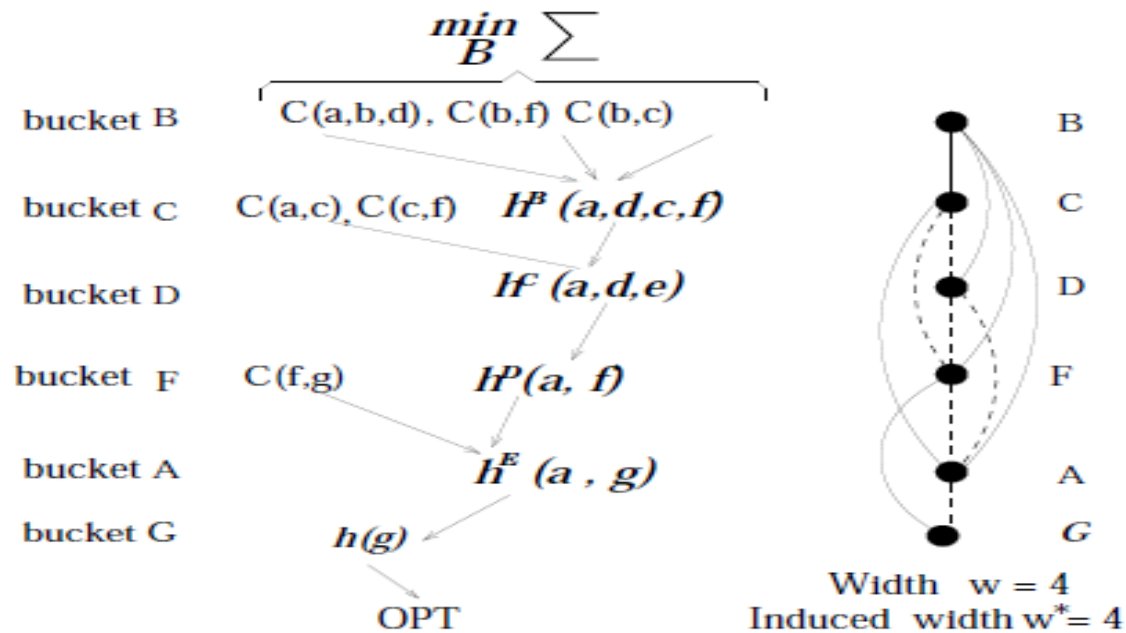
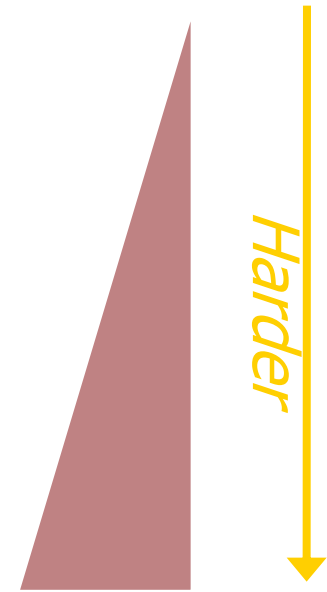


Figure 5.12: Schematic execution of BE-Opt

Marginal Map

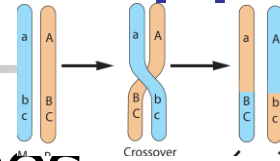
▶ Max-Inference	$f(\mathbf{x}^*) = \max_{\mathbf{x}} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$
▶ Sum-Inference	$Z = \sum_{\mathbf{x}} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$
▶ Mixed-Inference	$f(\mathbf{x}_M^*) = \max_{\mathbf{x}_M} \sum_{\mathbf{x}_S} \prod_{\alpha} f_{\alpha}(\mathbf{x}_{\alpha})$



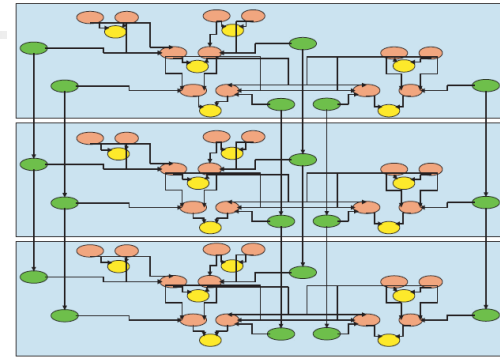
- **NP-hard**: exponentially many terms

Example for MMAP Applications

- Haplotype in Family pedigrees



6 people, 3 markers



- Coding networks

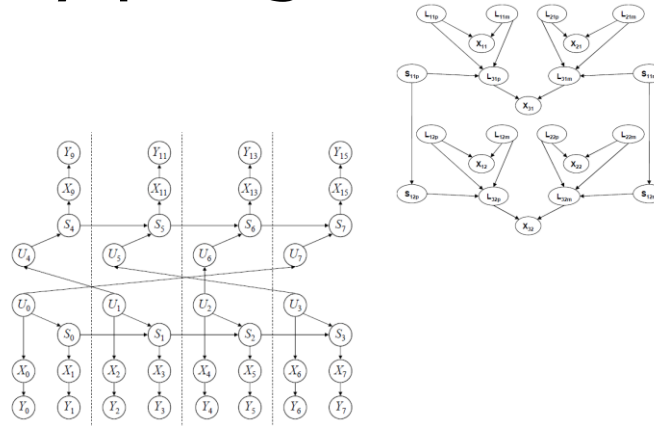
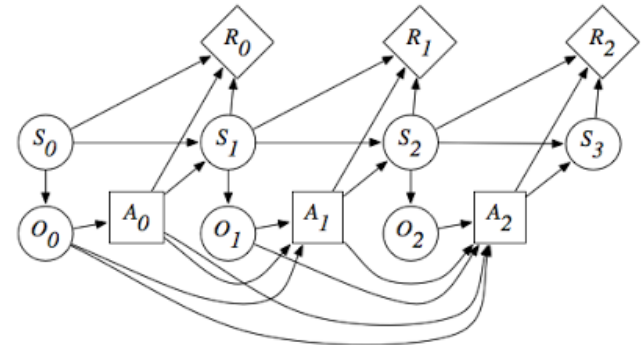
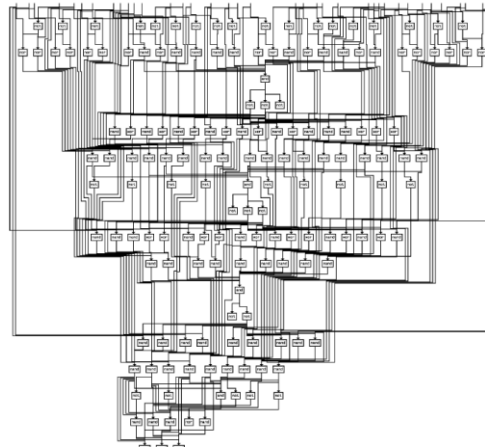


Figure 5.24: A Bayesian network for a turbo code.

- Probabilistic planning



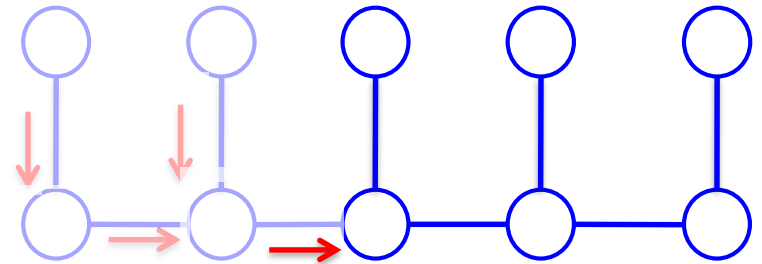
- Diagnosis



Marginal MAP is Not Easy on Trees

- Pure MAP or summation tasks

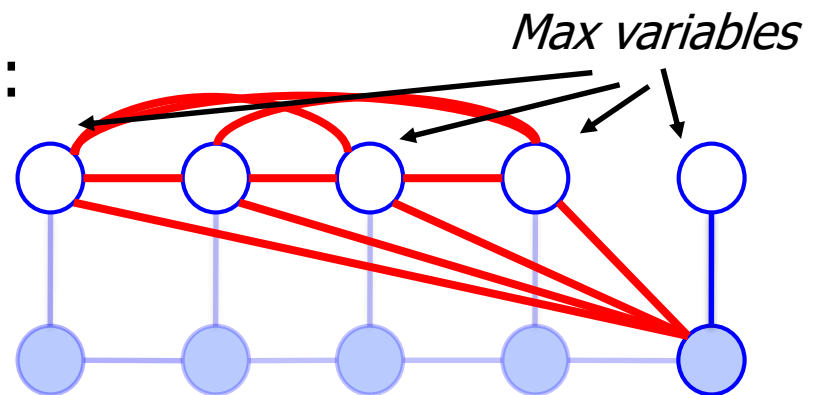
- Dynamic programming
- Ex: efficient on trees



- Marginal MAP

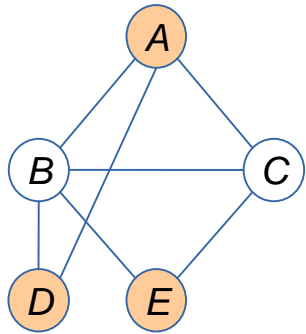
- Operations do not commute:
- Sum must be done first!

$$\sum \max \neq \max \sum$$



Bucket Elimination for MMAP

Bucket Elimination



$$\mathbf{X}_M = \{A, D, E\}$$

$$\mathbf{X}_S = \{B, C\}$$

$$\max_{\mathbf{X}_M} \sum_{\mathbf{X}_S} P(\mathbf{X})$$

constrained elimination order

SUM

MAX

$$B: \underbrace{f(A, B) f(B, C) f(B, D) f(B, E)}_{\Sigma_B}$$

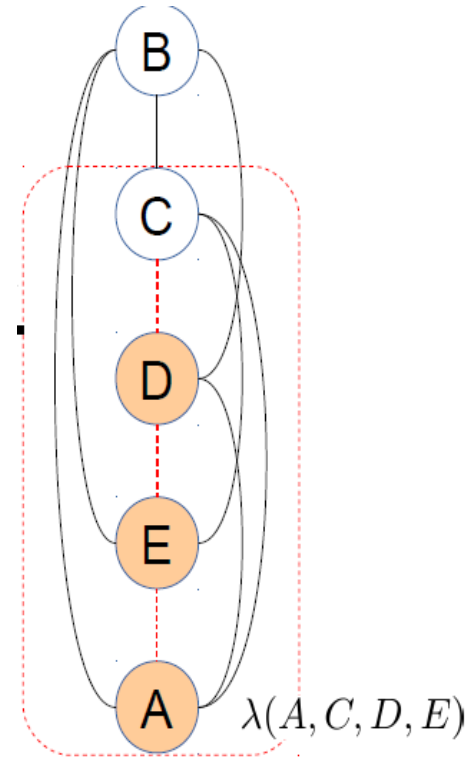
$$C: \underbrace{\lambda^B(A, C, D, E) f(A, C) f(C, E)}_{\Sigma_C}$$

$$D: \underbrace{\lambda^C(A, D, E) f(A, D)}_{\max_D}$$

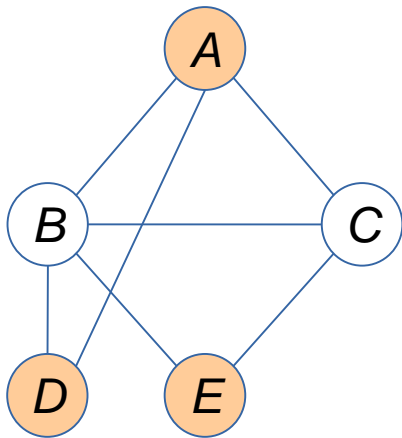
$$E: \underbrace{\lambda^D(A, E)}_{\max_E}$$

$$A: \underbrace{\lambda^E(A)}_{\text{MAP}^*}$$

MAP* is the marginal MAP value

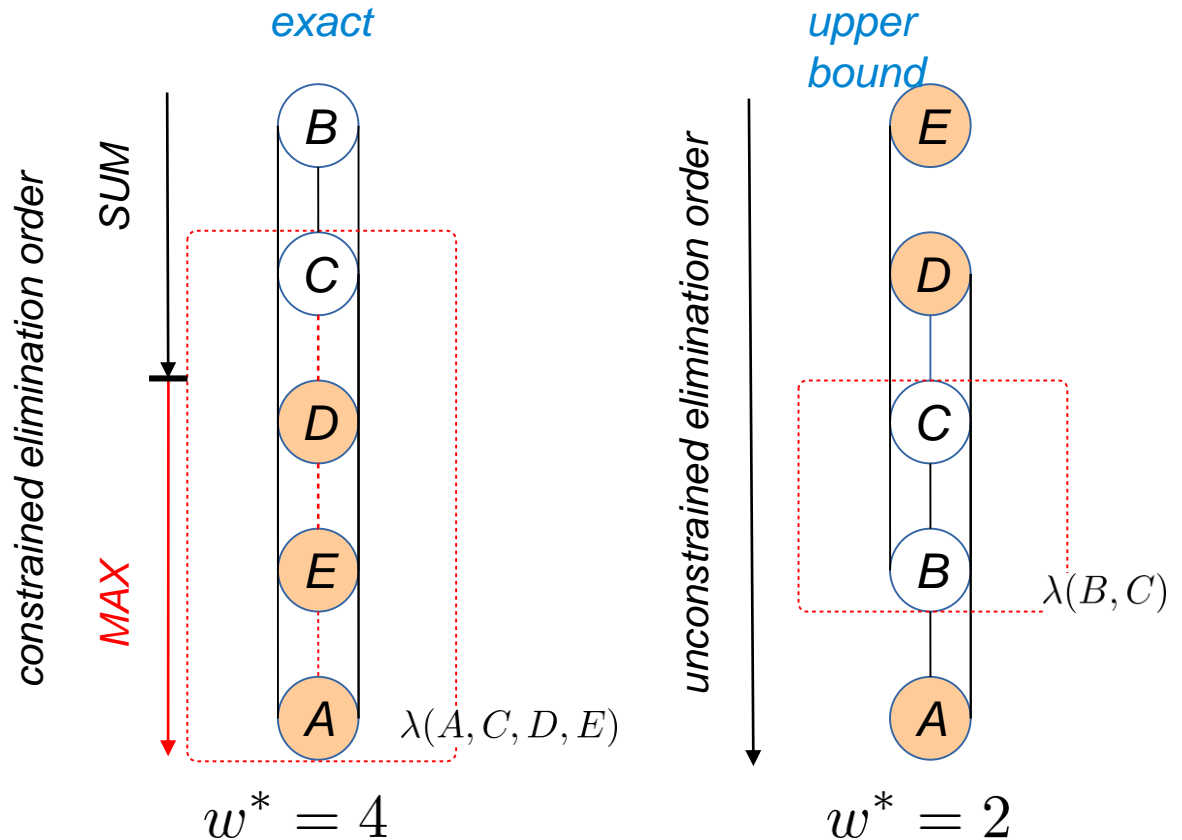


Why is MMAP harder?



$$\mathbf{X}_M = \{A, D, E\}$$

$$\mathbf{X}_S = \{B, C\}$$



In practice, constrained induced is much larger!

$$\max_X \sum_Y \phi \leq \sum_Y \max_X \phi$$

(Park & Darwiche, 2003)
(Yuan & Hansen, 2009)



Complexity of Bucket-Elimination

- **Theorem:**

BE is $O(n \exp(w^*+1))$ time and $O(n \exp(w^*))$ space, when w^* is the induced-width of the moral graph along d when evidence nodes are processed (edges from evidence nodes to earlier variables are removed.)

More accurately: $O(r \exp(w^(d)))$ where r is the number of CPTs.
For Bayesian networks $r=n$. For Markov networks?*



Inference with Markov Networks

- Undirected graphs with potentials on cliques
- Query: find *partition function*. Same as probability of the evidence in a Bayesian network.
- The joint probability distribution of a Markov network is defined by:

$$P(x) = \frac{1}{Z} \sum_{x \in \mathcal{D}} \prod_{C \in \mathcal{C}} \Psi_C(x_C)$$

BE is equally applicable

$$Z = \sum_x \prod_{C \in \mathcal{C}} \Psi_C(x_C) \quad (2.2)$$

For example. A markov network over the moral graph in Figure 2.4(b) is defined by:

$$P(a, b, c, d, f, g) = \frac{\Psi(a, b, c) \cdot \Psi(b, c, f) \cdot \Psi(a, b, d) \cdot \Psi(f, g)}{Z} \quad (2.3)$$

where,

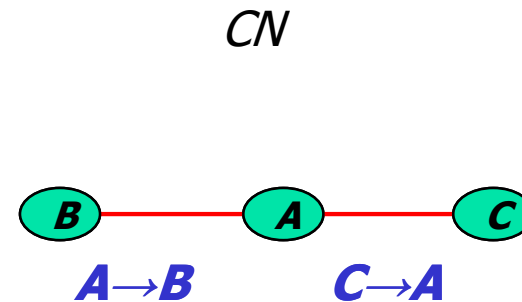
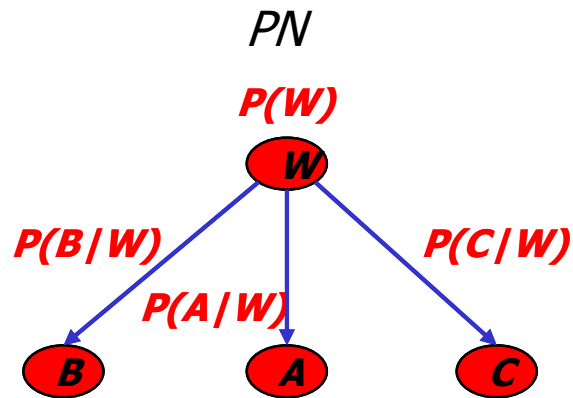
$$Z = \sum_{a,b,c,d,e,f,g} \Psi(a, b, c) \cdot \Psi(b, c, f) \cdot \Psi(a, b, d) \cdot \Psi(f, g) \quad (2.4)$$



Inference for probabilistic networks

- **Bucket elimination**
 - Belief-updating, $P(e)$, partition function
 - Marginals, probability of evidence
 - The impact of evidence
 - for MPE (\rightarrow MAP)
 - for MAP (\rightarrow Marginal Map)
 - Mixed networks
- Tree-decomposition schemes
 - Bucket tree elimination
 - Cluster tree elimination

Party Example



Semantics?

Algorithms?

Query:

Is it likely that Chris goes to the party if Becky does not but the weather is bad?

$$P(C, \neg B \mid w = \text{bad}, A \rightarrow B, C \rightarrow A)$$



Bucket Elimination for Mixed Networks

The CPE query

$$P_{\mathcal{B}}(\varphi) = \sum_{\mathbf{x}_{\varphi} \in \text{Mod}(\varphi)} P(\mathbf{x}_{\varphi})$$

Using the belief network product form we get:

$$P_{\mathcal{B}}(\varphi) = \sum_{\{\mathbf{x} | \mathbf{x}_{\varphi} \in \text{Mod}(\varphi)\}} \prod_{i=1}^n P(x_i | \mathbf{x}_{pa_i}).$$

$P((C \rightarrow B) \text{ and } (A \rightarrow C))$

Bucket-Elimination example

for a Mixed Network $\varphi = (BVC), (GVD), (\sim DV \sim B)$

In *Bucket_G* : $\lambda_G(f, d) = \sum_{\{g|g \vee d = \text{true}\}} P(g|f)$

In *Bucket_F* : $\lambda_F(b, c, d) = \sum_f P(f|b, c)\lambda_G(f, d)$

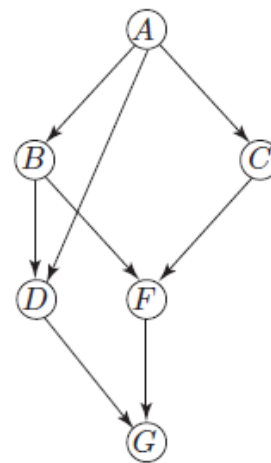
In *Bucket_D* : $\lambda_D(a, b, c) = \sum_{\{d|\neg d \vee \neg b = \text{true}\}} P(d|a, b)\lambda_F(b, c, d)$

In *Bucket_B* : $\lambda_B(a, c) = \sum_{\{b|b \vee c = \text{true}\}} P(b|a)\lambda_D(a, b, c)\lambda_F(b, c)$

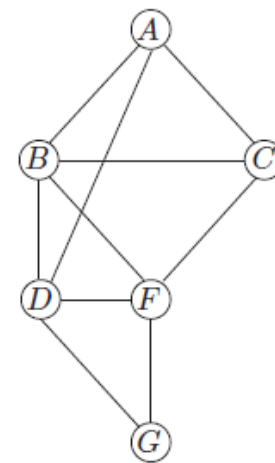
In *Bucket_C* : $\lambda_C(a) = \sum_c P(c|a)\lambda_B(a, c)$

In *Bucket_A* : $\lambda_A = \sum_a P(a)\lambda_C(a)$

$P(\varphi) = \lambda_A.$



(a) Directed Acyclic Graph



(b) Moral Graph

Bucket-Elimination example

for a Mixed Network $\varphi = (BVC), (GVD), (\sim DV \sim B)$

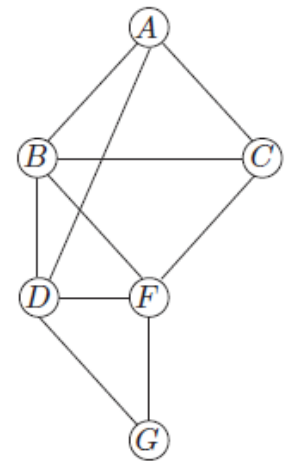
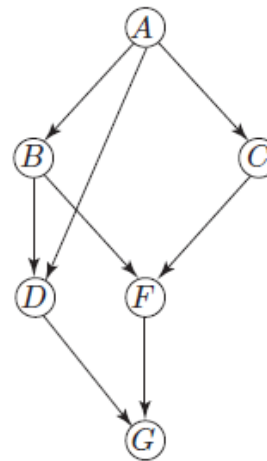
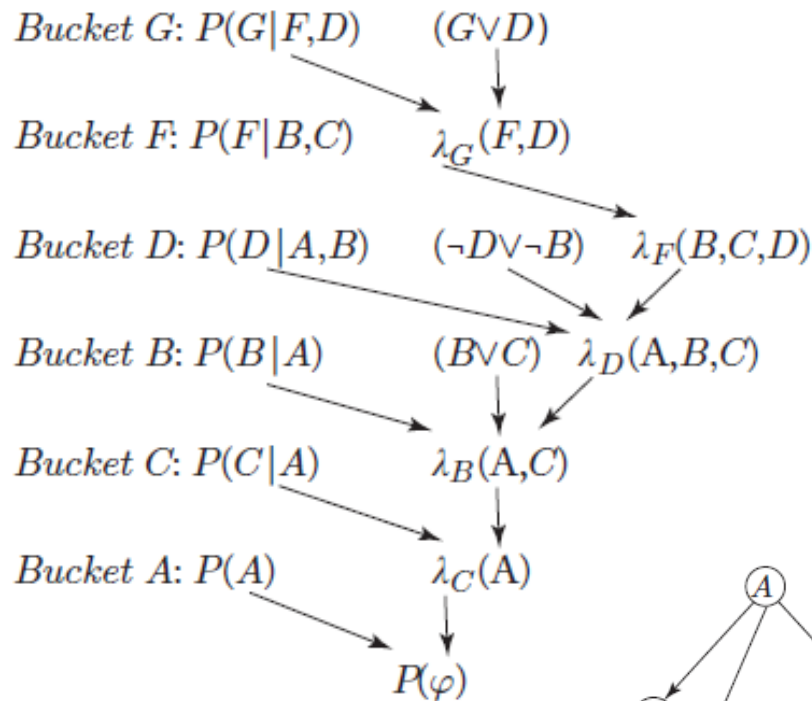


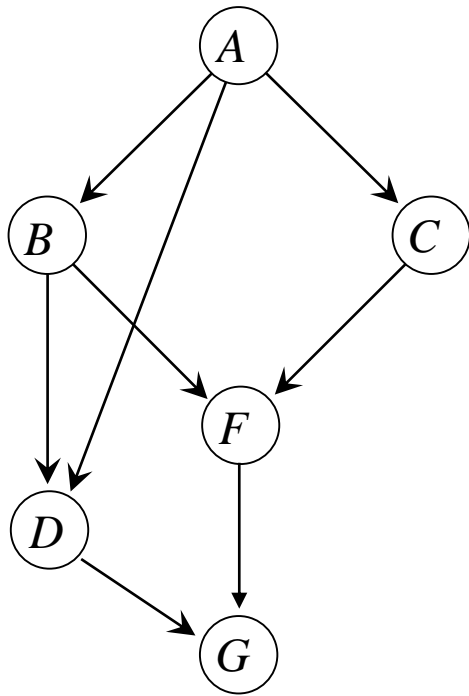
Figure 4.18: Execution of BE-CPE.

slides 7 8:

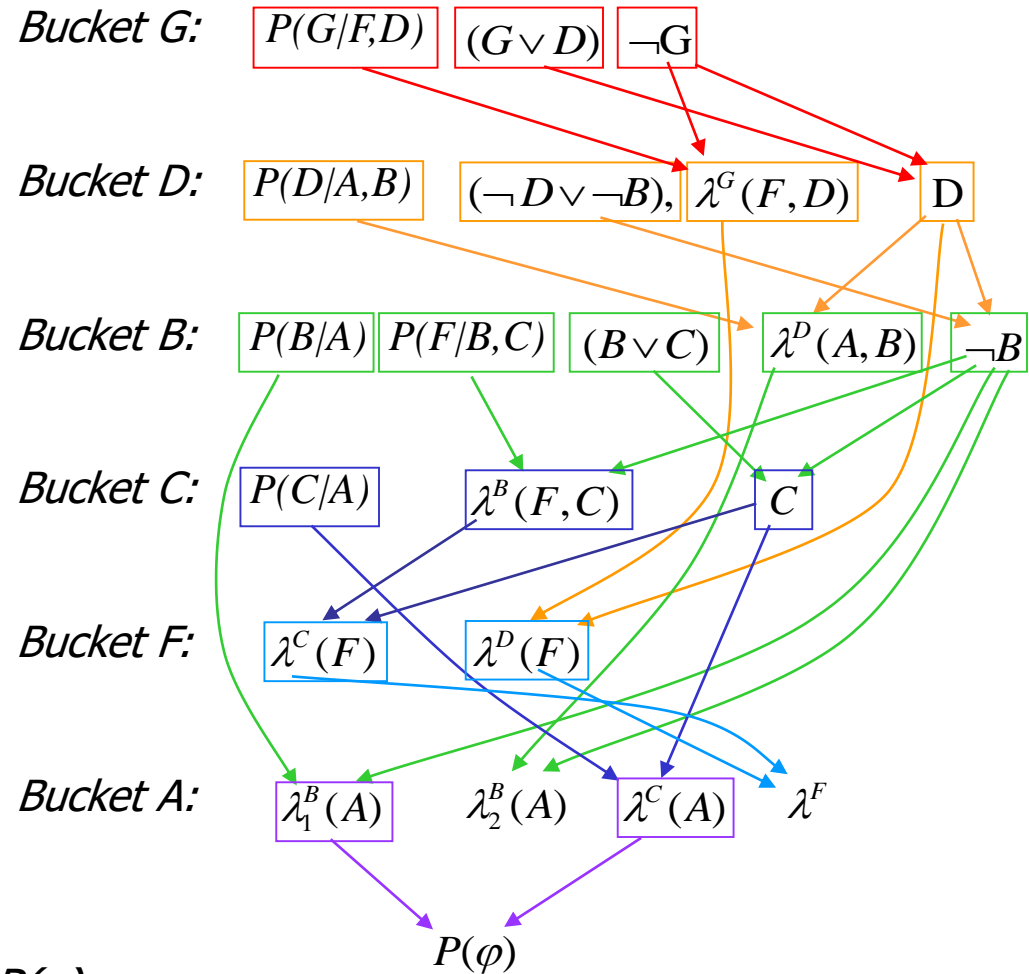
(a) Directed Acyclic Graph

(b) Moral Graph

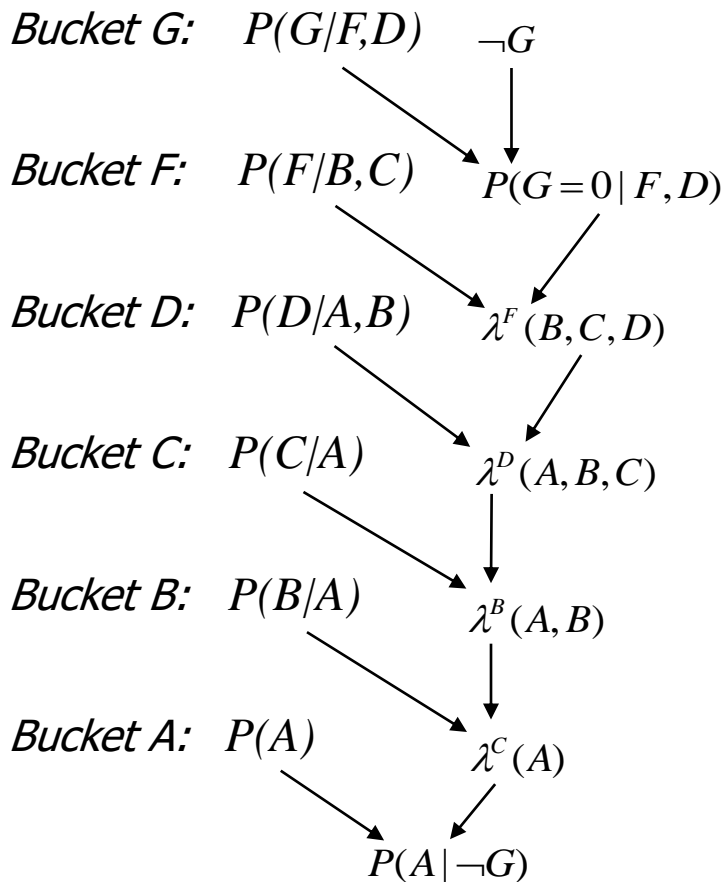
Trace of Elim-CPE



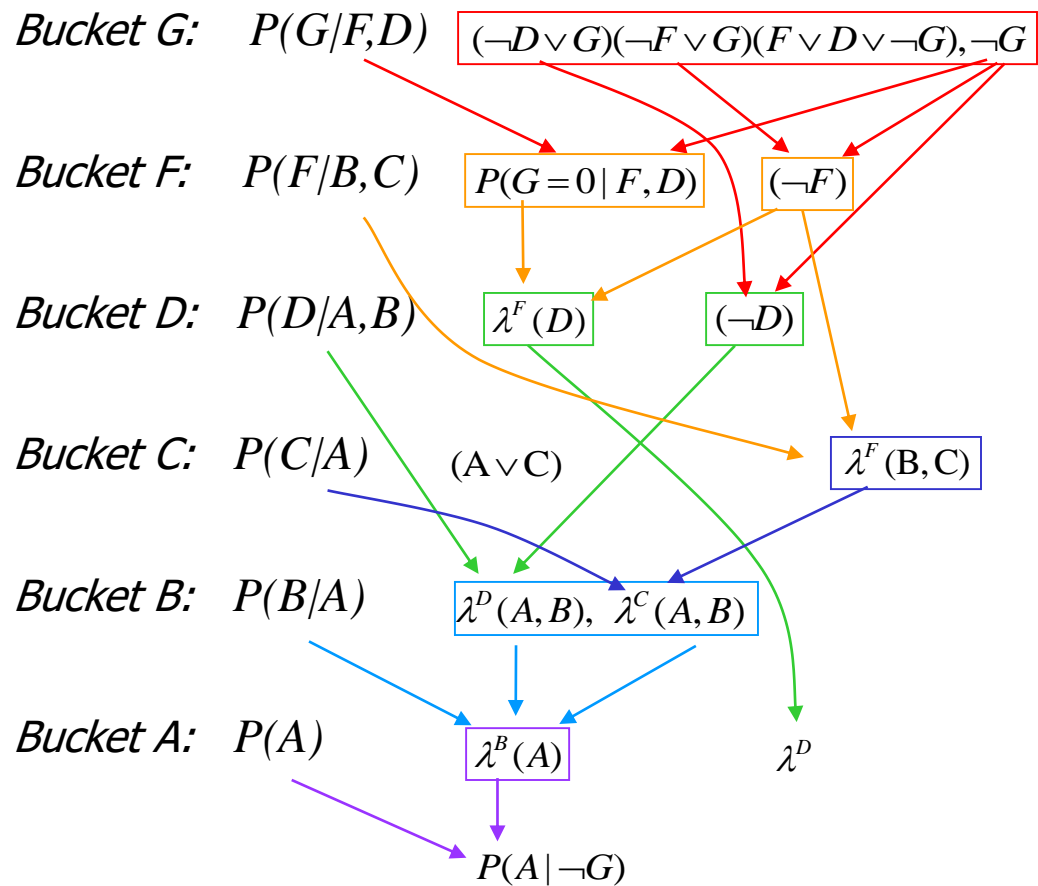
Belief network $P(g,f,d,c,b,a)$
 $=P(g|f,d)P(f|c,b)P(d|b,a)P(b|a)P(c|a)P(a)$



Bucket-Elimination for CPE



(a) regular Elim-CPE



(b) Elim-CPE-D with clause extraction

Bucket-Elimination example for a Mixed Network

$$\varphi = (BVC), (GVD), (\sim DV \sim B)$$

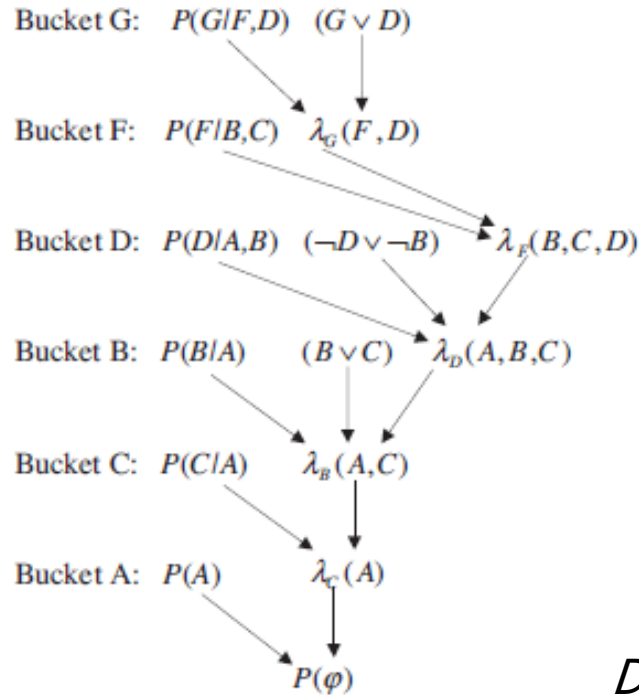
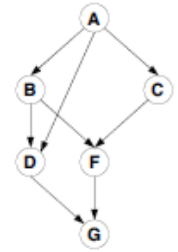


Figure 4.15: Execution of BE-CPE.

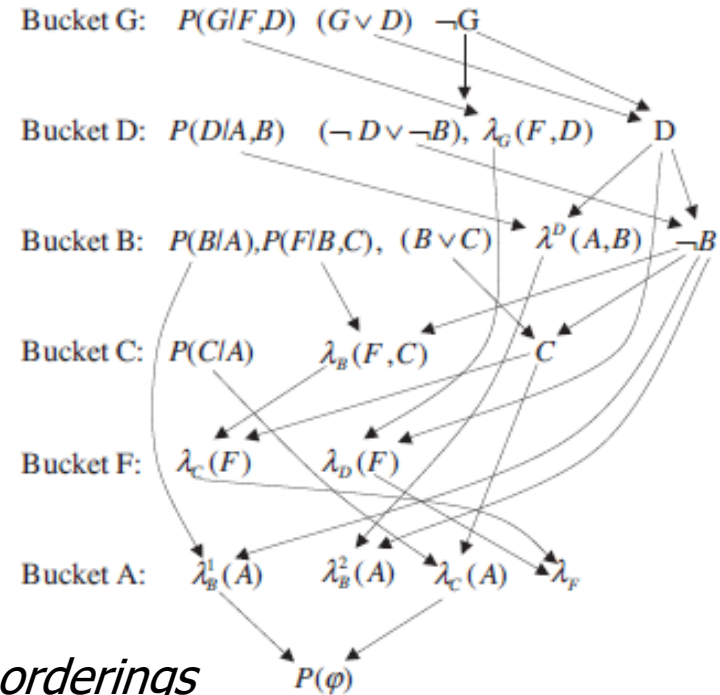


Figure 4.16: Execution of BE-CPE (evidence $\sim G$).

Bucket-Elimination example for a Mixed Network

$$\varphi = (B \vee C), (G \vee D), (\sim D \vee \sim B)$$

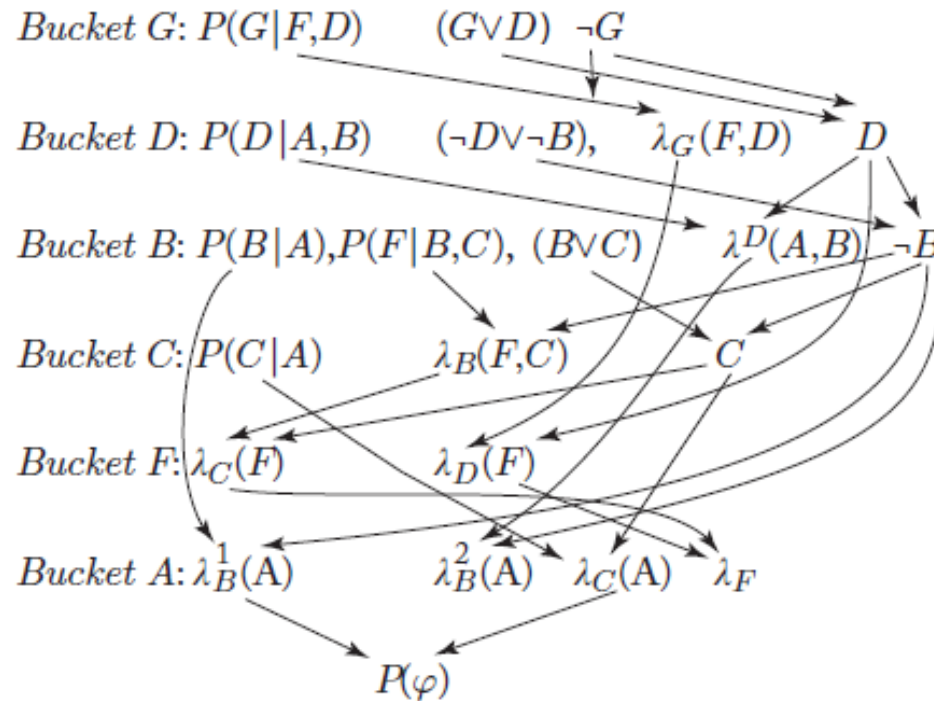
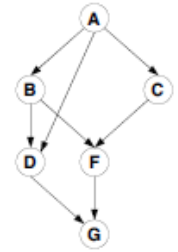


Figure 4.19: Execution of BE-CPE (evidence $\neg G$).