#### **Computational Geometry**



### *Delaunay Triangulations* **Michael Goodrich**

**with slides from Carola Wenk and David Eppstein**

# **Triangulation**

- Let  $P = \{p_1, ..., p_n\} \subseteq R^2$  be a finite set of points in the plane.
- A **triangulation of** *P* is a simple, plane (i.e., planar embedded), connected graph  $T=(P,E)$  such that
	- every edge in  $E$  is a line segment,
	- the outer face is bounded by edges of CH(*P*),
	- all inner faces are triangles.



# **Dual Graph**

- Let  $G = (V, E)$  be a plane graph. The dual graph  $G^*$  has
	- a vertex for every face of *G*,
	- an edge for every edge of *G*, between the two faces incident to the original edge



# **Delaunay Triangulation**

• Let *G* be the plane graph for the Voronoi diagram VD(*P*) . Then the dual graph  $G^*$  is called the **Delaunay Triangulation**  $DT(P)$ .



- If *P* is in general position (no three points on a line, no four points on a circle) then every inner face of  $DT(P)$  is indeed a triangle.
- DT(*P*) can be stored as an abstract graph, without geometric information. (No such obvious storing scheme for VD(*P*).)

# **Delaunay Triangulation**

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Canonical straight-line embedding for DT(P):



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# **Straight-Line Embedding**

- Lemma:  $DT(P)$  is a plane graph, i.e., the straight-line edges do not intersect. *q*
- **Proof:**  $\begin{bmatrix} p \end{bmatrix}$ 
	- $\overline{pp}$  is an edge of  $DT(P) \Leftrightarrow$  There is an empty closed disk  $D_p$  with  $p$  and  $p'$  on its boundary, and its center  $\vec{c}$  on the bisector.
	- Let  $\overline{q}$  be another Delaunay edge that intersects *pp'*

 $\Rightarrow$  *q* and *q*<sup>'</sup> lie outside of *D<sub><i>p*</sub></sub>, therefore *qq '* also intersects *pc* or *p'c*

- Symmetrically, *pp'* also intersects *qc'* or  $\overline{q'c}$
- $\Rightarrow$  (*pc* or  $\overline{p'c'}$ ) and (*qc*' or  $\overline{q'c}$ ) intersect
- $\Rightarrow$  The edges do not lie in different Voronoi cells.
- $\Rightarrow$  Contradiction



# **Characterization of DT(P)**

- Lemma: Let  $p, q, r \in P$  let  $\Delta$  be the triangle they define. Then the following statements are equivalent:
	- a)  $\triangle$  belongs to  $DT(P)$
	- b) The circumcenter *c* of  $\Delta$  is a vertex in  $VD(P)$
	- c) The circumcircle of  $\Delta$  is empty (i.e., contains no other point of *P*)

**Proof sketch:** All follow directly from the definition of DT(*P*) in VD(*P*). By definition of VD(*P*), we know that *p,q,r* are *c*'s nearest neighbors.

• **Characterization I**: Let *T* be a triangulation of *P*. Then  $T=DT(P) \Leftrightarrow$  The circumcircle of any triangle in *T* is empty.



#### **Application in scientific computing**

Commonly used in finite element mesh generation to generate a mesh after some other method (e.g. quadtrees, week 3) has been used to place points for vertices



#### **Application in geographic information systems**

Triangulation of points with elevations  $\Rightarrow$  surface in 3d

Given irregularly placed measurements of ground elevation, connect to form 3d model of ground surface

Called a "triangulated irregular net"



#### **Application in face recognition**

"DeepFace": used by Facebook to recognize people in photos from 2014 to 2021 (stopped for legal reasons, not technical problems)

Uses six points  $(2 \times e$ yes, nose,  $3 \times$  mouth) to fit 3d generic model

Map 67 "fiducial marks" on 3d model back to 2d image; Delaunay triangulate

Linearly map each triangle to warp to symmetric "frontal" appearance

Result is passed to a deep neural net









[Taigman et al. 2014]

#### **Euclidean minimum spanning tree**

Connect given points by a tree of minimum total edge length



#### **Applications of minimum spanning tree**

Original application: making physical connections between geographic locations (power grid) with low construction cost

Clustering: delete longest edge  $\Rightarrow$  two clusters as far from each other as possible

Generating a one-dimensional approximation to the shape of a cloud of points

Approximating traveling salesperson tour (tree traversal order gives tour of length  $\leq 2 \times$  optimal length)



#### Minimum spanning tree property

Every edge of the minimum spanning tree is in the DT



## **All Nearest Neighbors**

- All nearest neighbors: Find for each  $p \in P$  its nearest neighbor  $q \in P$ ;  $q \neq p$ .
	- **Empty circle property:**  $p, q \in P$  are connected by an edge in  $DT(P)$  $\Leftrightarrow$  there exists an empty circle passing through *p* and *q*. **Proof:** " $\Rightarrow$ ": For the Delaunay edge *pq* there must be a Voronoi edge. Center a circle through *p* and *q* at any point on the Voronoi edge, this circle must be empty. " $\leftarrow$ ": If there is an empty circle through p and q, then its center c

has to lie on the Voronoi edge because it is equidistant to *p* and *q* and there is no site closer to *c*.

- **Claim:** In  $DT(P)$ , every  $p \in P$  is adjacent to its nearest neighbors. **Proof:** Let  $q \in P$  be a nearest neighbor adjacent to p in  $DT(P)$ . Then the circle centered at  $p$  with  $q$  on its boundary has to be empty, so the circle with diameter *pq* is empty and *pq* is a Delaunay edge.
- **Algorithm:** Find all nearest neighbors in  $O(n)$  time: Check for each  $p \in P$  all points connected to p with a Delaunay edge.

*p*

*q*

*p q*

**Theorem:** Let  $P = \{p_1, \ldots, p_n\}$  with  $p_i = (a_i, b_i, 0)$ . Let  $p^*_{i} = (a_i, b_i, a_i^2 + b^2)$  $\mathbf{h}$ ) be the vertical projection of each point  $p_i$  onto the paraboloid  $z=x^2+y^2$ . Then  $DT(P)$ is the orthogonal projection onto the plane  $\zeta = 0$  of the lower convex hull of  $P^* = \{p^*_{1}, \ldots, p^*_{n}\}$ .



Pictures generated with Hull2VD tool available at http://www.cs.mtu.edu/~shene/NSF-2/DM2-BETA

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Slide adapted from slides by Vera Sacristan.